

Cloud capable and communicative rotary actuator for ball valves

- Torque motor 90 in-lb [10 Nm]
- Nominal voltage AC/DC 24 V
- Control modulating, Cloud, communicative, Hybrid
- Conversion of sensor signals
- Ethernet 10/100 Mbit/s, TCP/IP, integrated web server
- Communication via BACnet IP, Modbus TCP and Cloud



Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	4 W
	Power consumption in rest position	3 W
	Power consumption for wire sizing	6 VA
	Transformer sizing	6 VA (class 2 power source)
	Connection supply / control	cable 3 ft. [1 m], 6 x 0.5 mm ²
	Parallel operation	Yes (note the performance data)
	Electrical Connection	18 GA appliance cable, 1/2" conduit connector and RJ45 socket (ethernet)
	Overload Protection	electronic throughout 0...95° rotation
Functional data	Torque motor	90 in-lb [10 Nm]
	Communicative control	Cloud BACnet IP Modbus TCP
	Operating range Y	2...10 V
	Operating range Y note	Hybrid via 2...10 V
	Operating range Y variable	0.5...10 V
	Position accuracy	±5%
	Direction of motion motor	selectable with switch 0/1
	Manual override	external push button
	Angle of rotation note	adjustable with mechanical stop
	Running Time (Motor)	default 150 s, variable 70...220 s
	Running time motor variable	70...220 s
	Adaptation Setting Range	manual
	Noise level, motor	45 dB(A)
Position indication	Mechanically, pluggable	
Safety data	Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)
	Degree of protection IEC/EN	IP54
	Degree of protection note	IP54 when using protective cap or protective grommet for RJ45 socket

Degree of protection NEMA/UL	NEMA 1 UL Enclosure Type 1
EMC	CE according to 2014/30/EU
Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2014/30/EU and 2014/35/EU; Listed to UL 2043 - suitable for use in air plenums per Section 300.22(c) of the NEC and Section 602.2 of the IMC
Quality Standard	ISO 9001
Mode of operation	Type 1
Rated impulse voltage supply / control	0.8 kV
Ambient temperature	-22...122°F [-30...50°C]
Storage temperature	-40...176°F [-40...80°C]
Ambient humidity	max. 95% r.H., non-condensing
Servicing	maintenance-free
Weight	Weight 1.5 lb [0.68 kg]
Materials	Housing material UL94-5VA

Safety notes


- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insulation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

- Mode of operation** The actuator is controlled via the Cloud, BACnet IP or Modbus TCP and drives to the position defined by the control signal. Various data points can be written and read via the same interfaces.
Hybrid mode:
The actuator receives its analog control signal from the higher level controller and drives to the position defined. Using the Cloud, BACnet IP or Modbus TCP, various data points can be read and with the exception of the control signal written.
- Converter for sensors** Connection option for two sensors (passive sensor, active sensor or switching contact). The actuator serves as an analog/digital converter for the transmission of the sensor signal to the higher level system.
- Communication** The configuration can be carried out through the integrated web server (RJ45 connection to the web browser), by communicative means or via the Cloud.
Additional information regarding the integrated web server can be found in the separate documentation.

"Peer to Peer" connection

http://belimo.local:8080

The Notebook must be set to "DHCP".

Make sure that only one network connection is active.

Standard IP address:

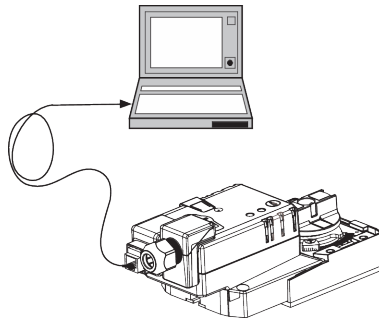
http://192.168.0.10:8080

Static IP address

Password (read-only):

User name: «guest»

Password: «guest»



Positioning signal inversion

This can be inverted in cases of control with an analog positioning signal. The inversion causes the reversal of the standard behavior, i.e. for control signal 0%, the actuator is opened to max and for control signal 100%, the actuator is closed.

Simple direct mounting

Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from revolving.

Data recording

The recorded data (integrated data recording for 13 months) can be used for analytical purposes. Download csv files via web browser.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaption, which is when the operating range and position feedback adjust themselves to the mechanical setting range.

The actuator then moves into the position defined by the positioning signal.

Adaptation and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button. Both mechanical end stops are detected during the adaption (entire setting range).

The actuator then moves into the position defined by the positioning signal.

Accessories

Electrical accessories	Description	Type
	Connection cable 16 ft [5 m], A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
Mechanical accessories	Description	Type
	Actuator arm for standard shaft clamp (one-sided)	AH-25
	Shaft extension 170 mm Ø10 mm for damper shaft Ø 6...16 mm	AV6-20
	Shaft extension 240 mm Ø20 mm for damper shaft Ø 8...22.7 mm	AV8-25
	Clamp NM/AM 1/2", 3/4", 1"	K-AM25
	Shaft clamp reversible, clamping range Ø8...20 mm	K-NA
	Ball joint suitable for damper crank arm KH8 / KH10	KG10A
	Ball joint suitable for damper crank arm KH8	KG6
	Ball joint suitable for damper crank arm KH8	KG8
	Damper crank arm Slot width 8.2 mm, clamping range Ø14...25 mm	KH10
	Damper crank arm Slot width 8.2 mm, for Ø1.05"	KH12
	Damper crank arm Slot width 6.2 mm, clamping range Ø10...18 mm	KH6
	Damper crank arm Slot width 8.2 mm, clamping range Ø10...18 mm	KH8
	Signal Simulator, Power supply AC 230 V	PS-100
	Push rod for KG10A ball joint (36" L, 3/8" diameter).	SH10
	Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).	SH8
	Anti-rotation bracket TF/NKQ/AM/NM/LM.	TF-P
	Wrench 8 mm and 10 mm	TOOL-06
	Base plate extension for NM..A to NM..., pcs.	Z-NMA
	Adapter for auxiliary switch and feedback potentiometer	Z-SPA

17" Mounting Bracket for AF,NF,GM,AM,SM	ZG-100
Mounting Bracket: AF,NF,LF,GM,AM,NM,SM	ZG-101
Mounting Bracket: ZS-260 Right Angle	ZG-109
Linkage kit	ZG-110
Jackshaft mounting bracket.	ZG-120
Damper clip for damper blade, 3.5" width.	ZG-DC1
Damper clip for damper blade, 6" width.	ZG-DC2
1" diameter jackshaft adaptor (11" L).	ZG-JSA-1
1-5/16" diameter jackshaft adaptor (12" L).	ZG-JSA-2
1.05" diameter jackshaft adaptor (12" L).	ZG-JSA-3
Mounting kit for linkage operation for flat installation	ZG-NMA
Shaft extension for 1/2" diameter shafts (3.8" L).	ZG-NMSA-1
Mounting plate for SGF.	ZG-SGF
Weather shield 13x8x6" [330x203x152 mm] (LxWxH)	ZS-100
Base Plate, for ZS-100	ZS-101
Weather shield 16x8-3/8x4" [406x213x102 mm] (LxWxH)	ZS-150
Explosion Proof Housing 16x10x6.435" [406x254x164 mm] (LxWxH), UL and CSA, Class I, Zone 1&2, Groups B, C, D, (NEMA 7), Class III, Hazardous (classified)	ZS-260
Locations	
Weather shield 17-1/4x8-3/4x5-1/2" [438x222x140 mm] (LxWxH), NEMA 4X, with mounting brackets	ZS-300
Weather shield 17-1/4x8-3/4x5-1/2" [438x222x140 mm] (LxWxH), NEMA 4X, with mounting brackets	ZS-300-5
Shaft extension 1/2"	ZS-300-C1
Shaft extension 3/4"	ZS-300-C2
Shaft extension 1"	ZS-300-C3

Service tools	Description	Type
	Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH US

Electrical installation

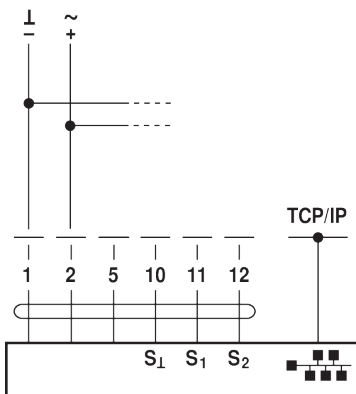


Connection via safety isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

Wiring diagrams

AC/DC 24 V



Cable colors:

- 1 = black
- 2 = red
- 5 = orange
- 10 = yellow-black
- 11 = yellow-pink
- 12 = yellow-grey



Connection of a notebook for parameterisation and manual control via RJ45.

Optional connection via RJ45 (direct connection Notebook / connection via Intranet or Internet) for access to the integrated web server

Functions

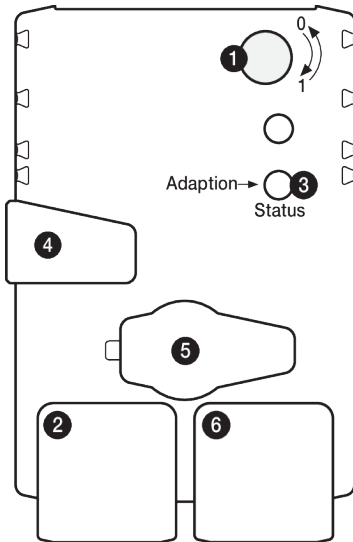


The connection diagrams shows connections for the first sensor on terminal S1, while the second sensor can be connected identically on terminal S2.

Parallel use of different sensor types is permitted.

For hybrid operation, S1 is used for the control signal Y and must be configured as an active sensor.

Operating controls and indicators



- 1** Direction of rotation switch
Switch: Direction of rotation changes
- 2** LED display green
Off: No power supply or wiring errors
On: Actuator starts operation
Flickering: In operation
- 3** Push-button and LED display orange
Off: Standard mode
On: Adaptation or synchronising process active
Press button: Triggers angle of rotation adaptation, followed by standard mode
- 4** Gear disengagement button
Press button: Gear disengages, motor stops, manual override possible
Release button: Gear engages, synchronization starts, followed by standard control mode
- 5** Service plug
Not used in this product
- 6** RJ45 socket
For the connection of TCP/IP (Cloud), BACnet/IP, and Modbus TCP

Dimensions

Dimensional drawings

