



5-year warranty



Technical data

<b>Electrical data</b>	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Power consumption in operation	2.5 W
	Power consumption in rest position	1.3 W
	Power consumption for wire sizing	5 VA
	Transformer sizing	5 VA (class 2 power source)
	Electrical Connection	18 GA appliance cable, 3 ft [1 m], with 1/2" conduit connector
	Overload Protection	electronic throughout 0...95° rotation
	Electrical Protection	actuators are double insulated
<b>Functional data</b>	Torque motor	22 in-lb [2.5 Nm]
	Direction of motion motor	selectable by ccw/cw mounting
	Direction of motion fail-safe	reversible with cw/ccw mounting
	Angle of rotation	Max. 95°
	Angle of rotation note	adjustable with mechanical stop
	Running Time (Motor)	75 s
	Running time fail-safe	<25 s @ -4...122°F [-20...50°C], <60 s @ -22°F [-30°C]
	Noise level, motor	50 dB(A)
	Noise level, fail-safe	62 dB(A)
	Shaft Diameter	1/4...1/2" round, centers on 1/2"
	Position indication	Mechanical
<b>Safety data</b>	Degree of protection IEC/EN	IP42
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2014/30/EU Listed to UL 2043 - suitable for use in air plenums per Section 300.22(C) of the NEC and Section 602 of the IMC
	Quality Standard	ISO 9001
	Ambient temperature	-22...122°F [-30...50°C]
	Storage temperature	-40...176°F [-40...80°C]
	Ambient humidity	Max. 95% RH, non-condensing
	Servicing	maintenance-free
	<b>Materials</b>	Housing material

**Footnotes** †Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 3

Product features

**Application** For On/Off, fail-safe control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer’s specifications. Control is On/Off from an auxiliary contact, or a manual switch. The actuator is mounted directly to a damper shaft from 1/4" up to 1/2" in diameter by means of its universal clamp, 1/2" shaft centered at delivery. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft.

**Operation** The TF series actuators provide true spring return operation for reliable fail-safe application and positive close off on air tight dampers. The spring return system provides consistent torque to the damper with, and without, power applied to the actuator. The TF series provides 95° of rotation and is provided with a graduated position indicator showing 0° to 90°. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. Power consumption is reduced in holding mode.

Safety Note: Screw a conduit fitting into the actuator’s bushing. Jacket the actuator’s input and output wiring with suitable flexible conduit. Properly terminate the conduit in a suitable junction box.

**Typical specification** On/Off spring return damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a shaft up to a 1/2" diameter and center a 1/2" shaft. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall be protected from overload at all angles of rotation. If required, one SPDT auxiliary switch shall be provided having the capability of being adjustable. Actuators with auxiliary switch must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed, have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Accessories

Electrical accessories	Description	Type
	Auxiliary switch, mercury-free	P475
	Signal simulator, Power supply AC 120 V	PS-100
	Cable conduit connector 1/2"	TF-CC US
	Transformer, AC 120 V to AC 24 V, 40 VA	ZG-X40

Mechanical accessories	Description	Type
	Shaft extension 170 mm Ø10 mm for damper shaft Ø 6...16 mm	AV6-20
	Position indicator for TFB(X)	IND-TF
	Shaft clamp for TFB(X)	K8 US
	Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG6
	Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG8
	Damper crank arm Slot width 8.2 mm, for Ø1.05"	KH12
	Damper crank arm Slot width 6.2 mm, clamping range Ø10...18 mm	KH6
	Damper crank arm Slot width 8.2 mm, clamping range Ø10...18 mm	KH8
	TFB(X) crankarm with 5/16" slot.	KH-TF US
	TFB(X) crankarm with 1/4" slot.	KH-TF-1 US
	Screw fastening kit	SB-TF
	Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).	SH8
	Anti-rotation bracket TF/NKQ/AM/NM/LM.	TF-P
	Wrench 0.32 in and 0.39 in [8 mm and 10 mm]	TOOL-06
	Angle of rotation limiter, with end stop	ZDB-TF
	Mounting bracket for TFB(X)	ZG-113
	Damper clip for damper blade, 3.5" width.	ZG-DC1
	Damper clip for damper blade, 6" width.	ZG-DC2
	Shaft extension for 3/8" diameter shafts (4" L).	ZG-LMSA-1
	Shaft extension for 1/2" diameter shafts (5" L).	ZG-LMSA-1/2-5
	TFB(X) crankarm adaptor kit (includes ZG-113).	ZG-TF112
	TFB(X) crankarm adaptor kit (T bracket included).	ZG-TF2
	Mounting kit for TFB(X)	ZG-TF3
	Weather shield 330x203x152 mm [13x8x6"] (LxBxH)	ZS-100
	Base plate, for ZS-100	ZS-101
	Weather shield 406x213x102 mm [16x8-3/8x4"] (LxWxH)	ZS-150

**Electrical installation**
**⚠ Warning! Live electrical components!**

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

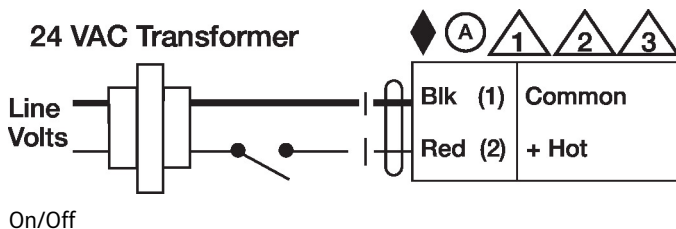
◆ Meets cULus requirements without the need of an electrical ground connection.

Ⓐ Actuators with appliance cables are numbered.

1 Provide overload protection and disconnect as required.

3 Actuators may also be powered by DC 24 V.

11 Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.



## Dimensions

