ZG-JSL, ZG-JSLA Jackshaft Retrofit Linkage

For Use with Belimo Rotary Actuators

5 YEAR WARRANTY

Application

The ZG-JSL jackshaft linkage is designed to easily attach to any part of a jackshaft and allow easy installation of select Belimo actuators. The unique open ended design and clamp insert allows the ZG-JSL to be used with any jackshaft from ½" to ¾" in diameter. Removal of the insert will allow the linkage to attach to a maximum shaft diameter of 1.05". Changing the antirotation plate will allow various actuators to be mounted.

Operation

The ¾" diameter built-in steel shaft allows direct coupling to the Belimo series actuators in the chart below. There is a torque reduction when using the ZG-JSL linkage. Verify application requirements before use.

Default/Configuration

The ZG-JSL linkage can also be configured by moving the anti-rotation plate 90° for space-saving applications. See mounting configurations below. The ZG-JSLA will have a factory mounted actuator on the linkage in the vertical position only.

Technical Data

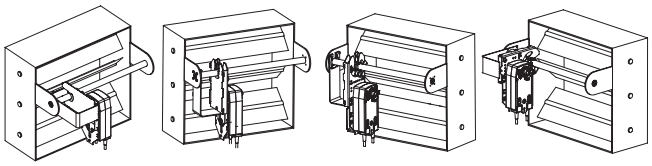
Stem	steel
Frame, plate, base	galanized steel
Housing material	galvanized steel
Bearing	GF Delrin
Mounting Position	90° to 180°
Ambient temperature	-22...122°F [-30...50°C]
Storage temperature	-40...176°F [-40...80°C]
Weight	5.2 lb [2.4 kg]

* ZG-121 adapter must be used with EF. ** GM/GK not for use with 1/2" shafts. *** K6-1 clamp must be used with LF. For close-off pressure reference Select Pro or Retrofit Technical Documentation.
For close-off pressure reference Select Pro or retrofit technical documentation.

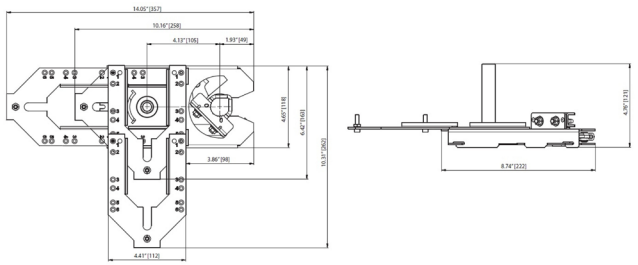
Suitable Actuators

	Non-Spring	Spring	Electronic fail-safe
ZG-JSL	AMB(X), GMB(X), NMB(X)	AF, EFB(X), LF, NF	NKQB(X)

Flow Pattern



Dimensions (Inches [mm])



LF24-SR US Technical Data Sheet

Modulating, Spring Return, AC 24 V/DC, for DC 2…10 V or 4…20 mA Control Signal

Torque min. 35 in-lb, for control of air dampers.

Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft from 3/8" up to 1/2" in diameter by means of its universal clamp, 1/2" shaft centered at delivery. For shafts up to 3/4" use K6-1 accessory. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft. The actuator operates in response to a 2 to 10 VDC, or with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication.

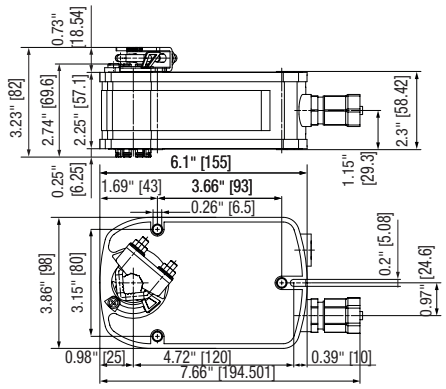
Operation

The LF series actuators provide true spring return operation for reliable fail-safe application and positive close-off on air tight dampers. The spring return system provides consistent torque to the damper with, and without, power applied to the actuator. The LF series provides 95° of rotation and is provided with a graduated position indicator showing 0 to 95°. The LF24-SR US uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. Power consumption is reduced in holding mode.

Technical Data	
Power Supply	24 VAC, ±20%, 50/60 Hz, 24 VDC, ±10%
Power consumption in operation	2.5 W
Power consumption in rest position	1 W
Transformer sizing	5 VA (class 2 power source)
Shaft Diameter	3/8...1/2" round, centers on 1/2"
Electrical Connection	18 GA plenum cable, 3 ft [1 m], with 1/2" conduit connector
Overload Protection	electronic throughout 0...95° rotation
Electrical Protection	actuators are double insulated
Operating Range	DC 2...10 V, 4...20 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)
Input Impedance	100 kΩ for DC 2...10 V (0.1 mA), 500 Ω for 4...20 mA
Position Feedback	DC 2...10 V, Max. 0.7 mA
Angle of rotation	Max. 95°,
Torque motor	35 in-lb [4 Nm]
Direction of rotation motor	reversible with built-in switch
Direction of motion fail-safe	reversible with cw/ccw mounting
Position indication	Mechanical
Running Time (Motor)	150 s constant, independent of load
Running time fail-safe	<25 s @ -4...122°F [-20...50°C], <60 s @ -22°F [-30°C]
Ambient humidity	max. 95% r.H., non-condensing
Ambient temperature	-22...122°F [-30...50°C]
Storage temperature	-40...176°F [-40...80°C]
Degree of Protection	IP54, NEMA 2
Housing material	galvanized steel
Agency Listing	cULus acc. To UL 873 and CAN/CSA C22.2 No. 24-93
Noise level, motor	30 dB(A)
Noise level, fail-safe	62 dB(A)
Servicing	maintenance-free
Quality Standard	ISO 9001
Weight	3.4 lb [1.5 kg]

†Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 3

Dimensions (Inches[mm])



Safety Notes

WARNING: For Belimo products sold in California: these products do or may contain chemicals which are known to the State of California to cause cancer and or birth defects or other reproductive harms. For more information see www.p65warnings.ca.gov.

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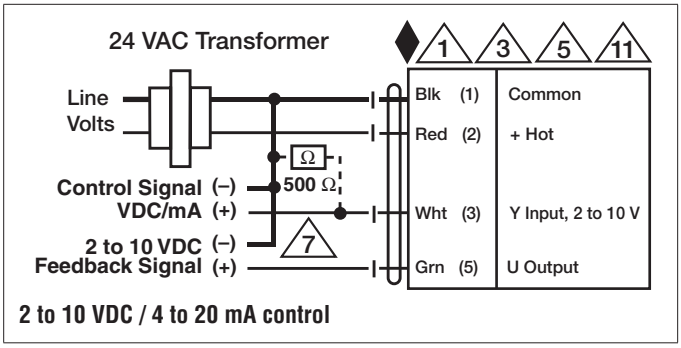
Accessories	
AV6-20	Shaft extension
K6 US	Standard LF clamp (3/8” to 1/2”).
K6-1	Shaft clamp reversible
KG10A	Ball joint
KG8	Ball joint
KH8	Damper crank arm
KH-LF	Actuator arm
KH-LFV	V-bolt Kit for KH-LF.
LF-P	Anti-rotation bracket LF.
SH10	Push rod for KG10A ball joint (36” L, 3/8” diameter).
SH8	Push rod for KG6 & KG8 ball joints (36” L, 5/16” diameter).
TOOL-06	8 mm and 10 mm wrench.
ZDB-LF	Angle of rotation limiter
ZF8-LF	Form fit adapter
ZG-109	Right angle bracket for ZS-260.
ZG-110	Stand-off bracket for ZS-260.
ZG-112	LF right angle bracket 4-1/2x5-1/2x2-1/2” (HxWxD).
ZG-DC1	Damper clip for damper blade, 3.5” width.
ZG-DC2	Damper clip for damper blade, 6” width.
ZG-LF112	LF crankarm adaptor kit (includes ZG-112).
ZG-LF2	LF crankarm adaptor kit (T bracket included).
ZG-LMSA-1	Shaft extension for 3/8” diameter shafts (4” L).
ZG-LMSA-1/2-5	Shaft extension for 1/2” diameter shafts (5” L).
ZS-100	Weather shield - galvaneal 13x8x6” (LxWxD).
ZS-101	Base plate for ZS-100.
ZS-150	Weather shield - PC w/ foam seal 16x8-3/8x4” (LxWxD).
ZS-260	Explosion proof housing.
ZS-300	NEMA 4X, 304 stainless steel enclosure.
ZS-300-5	NEMA 4X, 316L stainless steel enclosure.
ZS-300-C1	1/2” shaft adaptor, standard wtih ZS-300(-5).
ZS-300-C2	3/4” shaft adaptor for ZS-300(-5).
ZS-300-C3	1” shaft adaptor for ZS-300(-5).
ADS-100	Analog to digital switch for modulating actuators.
IRM-100	Input rescaling module for modulating actuators.
P475	Shaft mount, non-Mercury aux. switch for 1/2” dia. shafts.
P475-1	Shaft mount, non-Mercury aux. switch for 1” dia. shafts.
PS-100	Actuator power supply and control simulator.
PTA-250	Pulse width modulation interface for modulating actuators.
SGA24	Positioners suitable for use with the modulating damper actuators LM..A-SR, NM..A-SR, SM..A-SR and GM..A-SR
SGF24	Positioners suitable for use with the modulating damper actuators LM..A-SR, NM..A-SR, SM..A-SR and GM..A-SR
ZG-R01	4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6” pigtail wires.
ZG-R02	50% voltage divider kit (resistors with wires).
ZG-SGF	Mounting plate for SGF.
ZG-X40	120 to 24 VAC, 40 VA transformer.



2 to 10 VDC / 4 to 20 mA control

LF24-SR US Technical Data Sheet

Modulating, Spring Return, AC 24 V/DC, for DC 2…10 V or 4…20 mA Control Signal

Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a shaft up to a 3/4" diameter and center on a 1/2" shaft (default). Actuator shall deliver a minimum output torque of 35 in-lbs. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 feedback signal shall be provided for position feedback. The actuator must be designed so that they may be used for either clockwise or counter clockwise failsafe operation. Actuators shall be cULus listed, have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Wiring Diagrams

WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

Meets cULus requirements without the need of an electrical ground connection.

1 Provide overload protection and disconnect as required.

3 Actuators may also be powered by 24 VDC.

5 Only connect common to negative (-) leg of control circuits.

7 A 500 Ω resistor (ZG-R01) converts the 4 to 20 mA control signal to 2 to 10 VDC.

11 Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.