

Modulating linear actuator for adjusting dampers and slide valves in technical building equipment

- Actuating force 125 N
- Nominal voltage AC/DC 24 V
- Control modulating 2...10 V
- Position feedback 2...10 V
- Length of Stroke Max. 60 mm, adjustable in 20 mm increments



Technical data

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|--------------------------|------------------------------------|---|
| Electrical data | Nominal voltage | AC/DC 24 V |
| | Nominal voltage frequency | 50/60 Hz |
| | Nominal voltage range | AC 19.2...28.8 V / DC 19.2...28.8 V |
| | Power consumption in operation | 1 W |
| | Power consumption in rest position | 0.5 W |
| | Power consumption for wire sizing | 1.5 VA |
| | Connection supply / control | Cable 1 m, 4x 0.75 mm ² |
| | Parallel operation | Yes (note the performance data) |
| Functional data | Actuating force motor | 125 N |
| | Operating range Y | 2...10 V |
| | Input impedance | 100 kΩ |
| | Position feedback U | 2...10 V |
| | Position feedback U note | Max. 1 mA |
| | Position accuracy | ±5% |
| | Direction of motion motor | Y = 0 V: extended |
| | Manual override | with magnet |
| | Stroke | 60 mm |
| | Length of Stroke | Max. 60 mm, adjustable in 20 mm increments |
| | Stroke limitation | can be limited on both sides with mechanical end stops |
| | Running time motor | 380 s / 100 mm |
| | Running time motor note | corresponds to 230 s / 60 mm |
| Sound power level, motor | 35 dB(A) | |
| Safety data | Protection class IEC/EN | III, Safety Extra-Low Voltage (SELV) |
| | Power source UL | Class 2 Supply |
| | Degree of protection IEC/EN | IP54 |
| | Degree of protection NEMA/UL | NEMA 2 |
| | Enclosure | UL Enclosure Type 2 |
| | EMC | CE according to 2014/30/EU |
| | Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 |
| | UL Approval | cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 The UL marking on the actuator depends on the production site, the device is UL-compliant in any case |
| | Hygiene test | According to VDI 6022 Part 1 / SWKI VA 104-01, cleanable and disinfectable, low emission |
| | Type of action | Type 1 |

Technical data

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| Safety data | Rated impulse voltage supply / control | 0.8 kV |
| | Pollution degree | 3 |
| | Ambient humidity | Max. 95% RH, non-condensing |
| | Ambient temperature | -30...50°C [-22...122°F] |
| | Storage temperature | -40...80°C [-40...176°F] |
| | Servicing | maintenance-free |
| Weight | Weight | 0.38 kg |
| | Packaging quantity | Multipack 20 pcs. |

Safety notes


- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insulation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- The rotary supports and coupling pieces are available as accessories and must always be used if transverse forces are likely. An additional installation sheet is required in accordance with the installation instructions. In addition, the actuator must not be tightly bolted to the application. It must remain movable via the rotary support (refer to "Installation notes").
- If the actuator is exposed to severely contaminated ambient air, appropriate precautions must be taken on the system side. Excessive deposits of dust, soot etc. can prevent the gear rod from being extended and retracted correctly.
- If the actuator is not installed horizontally, the magnet-operated gear train disengagement may only be actuated when there is no pressure on the gear rod.
- To calculate the actuating force required for air dampers and slide valves, the specifications supplied by the damper manufacturers concerning the cross-section and the design, as well as the installation situation and the ventilation conditions must be observed.
- If a rotary support and/or coupling piece is used, actuation force losses are to be expected.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

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|-------------------------------|---|
| Mode of operation | The actuator is connected with a standard control signal of 0...10 V and drives to the position defined by the control signal. Measuring voltage U serves for the electrical display of the damper position 0...100% and as control signal for other actuators. |
| Simple direct mounting | The actuator can be directly connected with the application using the enclosed screws. The head of the gear rod is connected to the moving part of the ventilating application individually on the mounting side or with the Z-KS2 coupling piece provided. |
| Manual override | Manual override with magnet possible (gear train disengagement as long as the magnet adheres to the magnet symbol). The Z-MA magnet for the gear train disengagement is enclosed. |

Product features

- Adjustable stroke** If a stroke limitation will be adjusted, the mechanical operating range on this side of the gear rod can be used starting with an extension length of 20 mm and then can be limited respectively in increments of 20 mm by means of mechanical end stops Z-AS2.
 If the stroke limiters are used with the motor (with end stop clip Z-ESCM), the operating range can be limited on both sides. It can be adjusted in increments of 0.5 mm (calculatory 0.55 mm) from 0...40/60/67.5 mm.
- High functional reliability** The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
- Hidden synchronisation** If the actuator drives to the lower end stop during ongoing operation, it performs a synchronisation of the control signal at DC 2 V. This ensures that the signal range also corresponds to the effective functional range in ongoing operation. The bottom end stop is actively approached as soon as the control signal is <DC 2.1 V. The actuator drives to the new specified position as soon as the control signal is once again >DC 2.3 V.

Accessories

| Mechanical accessories | Description | Type |
|------------------------|--|--------|
| | End stop kit, Multipack 20 pcs. | Z-AS2 |
| | Rotary support, for linear actuator, for compensation of transverse forces | Z-DS1 |
| | End stop clip, Multipack 20 pcs. | Z-ESCM |
| | Spring clip, Multipack 20 pcs. | Z-FKCH |
| | Coupling piece M6 | Z-KS2 |
| | Gear train disengagement magnet, Multipack 20 pcs. | Z-MA |

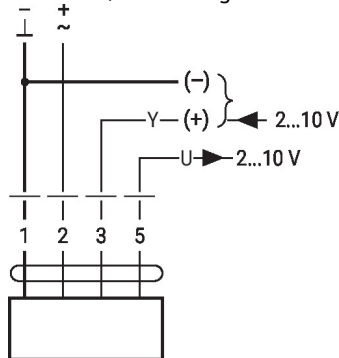
Electrical installation

Supply from isolating transformer.
Parallel connection of other actuators possible. Observe the performance data.
Wire colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

Wiring diagrams

AC/DC 24 V, modulating



| | | | |
|---|---|------|---|
| 1 | 2 | 3 | |
| — | — | 2 V | ↑ |
| — | — | 10 V | ↓ |

Installation notes

If a rotary support and/or coupling piece is used, losses in the actuation force losses are to be expected.

Installation notes

Applications without transverse forces The linear actuator is screwed directly to the housing at two points. Afterwards, the head of the gear rod is fastened to the moving part of the ventilation application (e.g. damper or slide valve).

Applications with transverse forces Connect the coupling piece with the internal thread (Z-KS2) to the head of the gear rod. Screw the rotary support (Z-DS1) to the ventilation application. Afterwards, the linear actuator is screwed to the previously mounted rotary support with the enclosed screw. Then, the coupling piece, which is mounted to the head of the gear rod, is attached to the moving part of the ventilating application (e.g. damper or slide valve). The transverse forces can be compensated for to a certain limit with the rotary support and/or coupling piece. The maximum permissible swivel angle of the rotary support and coupling piece is 10°, laterally and upwards.

Negative force If end stop clips (Z-ESCM) are used the following applies: ≤50% of the actuating force (Caution: Use possible only with restrictions. Please contact your supplier.)

If end stops are used on the gear rod or at the application no restrictions apply.

Dimensions

