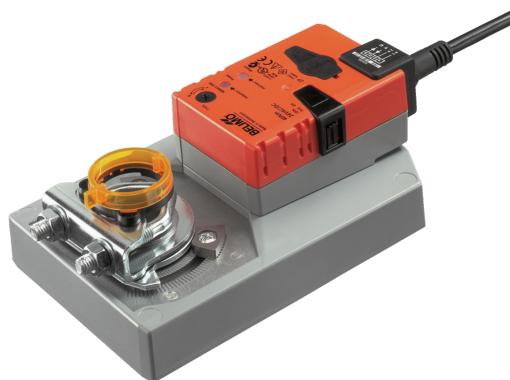


Communicative damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 8 m<sup>2</sup>
- Torque motor 40 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative, hybrid
- Communication via BACnet MS/TP, Modbus RTU, Belimo-MP-Bus or conventional control
- Conversion of sensor signals



Picture may differ from product

### Technical data

#### Electrical data

Nominal voltage	AC/DC 24 V
Nominal voltage frequency	50/60 Hz
Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
Power consumption in operation	3.5 W
Power consumption in rest position	1.6 W
Power consumption for wire sizing	5.5 VA
Connection supply / control	Cable 1 m, 6x 0.75 mm <sup>2</sup>

#### Data bus communication

Communicative control	BACnet MS/TP Modbus RTU (factory setting) MP-Bus
Number of nodes	BACnet / Modbus see interface description MP-Bus max. 8

#### Functional data

Torque motor	40 Nm
Torque variable	25%, 50%, 75% reduced
Operating range Y	2...10 V
Operating range Y variable	0.5...10 V
Position feedback U	2...10 V
Position feedback U note	Max. 1 mA
Position feedback U variable	Start point 0.5...8 V End point 2...10 V
Position accuracy	±5%
Direction of motion motor	selectable with switch 0/1
Direction of motion variable	electronically reversible
Direction of motion note	Y = 0%: At switch position 0 (ccw rotation) / 1 (cw rotation)
Manual override	with push-button, can be locked
Angle of rotation	Max. 95°
Angle of rotation note	can be limited on both sides with adjustable mechanical end stops
Running time motor	150 s / 90°
Running time motor variable	75...290 s
Sound power level, motor	45 dB(A)
Adaptation setting range	manual
Adaptation setting range variable	No action Adaptation when switched on Adaptation after pushing the manual override button
Override control, controllable via bus communication	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position) = 50%

## Technical data

<b>Functional data</b>	Override control variable	MAX = (MIN + 32%)...100% MIN = 0%...(MAX - 32%) ZS = MIN...MAX
	Mechanical interface	Universal shaft clamp 12...26.7 mm
	Position indication	Mechanical, pluggable
<b>Safety data</b>	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)
	Power source UL	Class 2 Supply
	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Housing	UL Enclosure Type 2
	EMC	CE according to 2014/30/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	UL Approval	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 The UL marking on the actuator depends on the production site, the device is UL-compliant in any case
	Hygiene test	According to VDI 6022 Part 1
	Type of action	Type 1
	Rated impulse voltage supply / control	0.8 kV
	Pollution degree	3
	Ambient humidity	Max. 95% RH, non-condensing
	Ambient temperature	-30...50°C [-22...122°F]
	Storage temperature	-40...80°C [-40...176°F]
	Servicing	maintenance-free
<b>Weight</b>	Weight	1.7 kg

## Safety notes

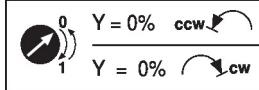


- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: Only possible if no (sea) water, snow, ice, sunlight or aggressive gases act directly on the device and if it is ensured that the ambient conditions remain within the limit values specified in the data sheet at all times.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section and the design, as well as the installation situation and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

## Product features

<b>Operating mode</b>	The actuator is fitted with an integrated interface for BACnet MS/TP, Modbus RTU and MP-Bus. It receives the digital control signal from the control system and returns the current status.
<b>Converter for sensors</b>	Connection option for a sensor (passive, active or with switching contact). In this way, the analogue sensor signal can be easily digitised and transferred to the bus systems : BACnet, Modbus or MP-Bus.

## Product features

<b>Configurable device</b>	The factory settings cover the most common applications. Single parameters can be modified with Belimo Assistant 2.
<b>Combination analogue - communicative (hybrid mode)</b>	With conventional control by means of an analogue control signal, BACnet or Modbus can be used for the communicative position feedback
<b>Simple direct mounting</b>	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation mechanism to prevent the actuator from rotating.
<b>Manual override</b>	Manual override with push-button possible (the gear train is disengaged for as long as the button is pressed or remains locked).
<b>Adjustable angle of rotation</b>	Adjustable angle of rotation with mechanical end stops.
<b>High functional reliability</b>	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
<b>Home position</b>	<p>The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).</p> <p>The actuator then moves into the position defined by the control signal.</p>
	
<b>Adaptation and synchronisation</b>	<p>An adaptation can be triggered manually by pressing the "Adaptation" button or with Belimo Assistant 2. Both mechanical end stops are detected during the adaptation (entire setting range).</p> <p>Automatic synchronisation after pressing the manual override button is configured. The synchronisation is in the home position (0%).</p> <p>The actuator then moves into the position defined by the control signal.</p> <p>A range of settings can be made using Belimo Assistant 2.</p>

## Accessories

Tools	Description	Type
	Service tool for wired and wireless setup, on-site operation and troubleshooting.	Belimo Assistant 2
	Belimo Assistant Link Bluetooth and USB to NFC and MP-Bus converter for configurable and communicative devices	LINK.10
	Connecting cable 5 m, A: RJ11 6/4 LINK.10, B: 6-pin for connection to service socket	ZK1-GEN
	Connecting cable 5 m, A: RJ11 6/4 LINK.10, B: free wire end for connection to MP/PP terminal	ZK2-GEN
Electrical accessories	Description	Type
	Auxiliary switch 1x SPDT add-on	S1A
	Auxiliary switch 2x SPDT add-on	S2A
	Feedback potentiometer 140 $\Omega$ add-on	P140A
	Feedback potentiometer 1 k $\Omega$ add-on	P1000A
	Feedback potentiometer 10 k $\Omega$ add-on	P10000A
Mechanical accessories	Description	Type
	Actuator arm for standard shaft clamp	AH-GMA
	Ball joint suitable for damper crank arm KH8 / KH10	KG10A
	Damper crank arm Slot width 8.2 mm, clamping range $\varnothing$ 14...25 mm	KH10
	Anti-rotation mechanism 230 mm, Multipack 20 pcs.	Z-ARS230
	Mounting kit for linkage operation for flat installation	ZG-GMA
	Baseplate extension for GM..A to GM..	Z-GMA
	Position indicator, Multipack 20 pcs.	Z-PI

## Electrical installation



Supply from isolating transformer.

The wiring of the line for BACnet MS/TP / Modbus RTU is to be carried out in accordance with applicable RS-485 regulations.

Modbus / BACnet: Supply and communication are not galvanically isolated. COM and ground of the devices must be connected to each other.

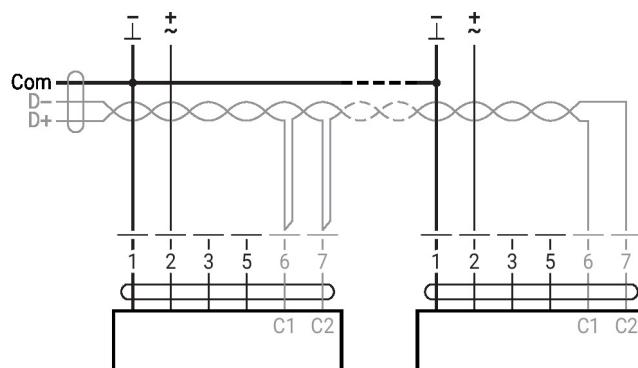
## Wire colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange
- 6 = pink
- 7 = grey

## Functions:

- C1 = D- (wire 6)
- C2 = D+ (wire 7)

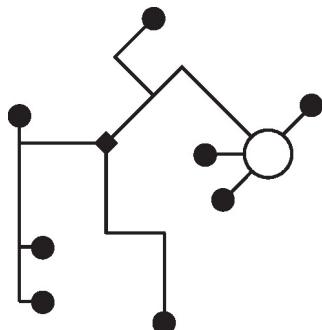
## BACnet MS/TP / Modbus RTU



## Further electrical installations

## MP-Bus

## MP-Bus Network topology

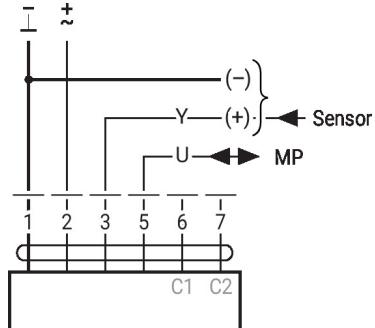


There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).

Supply and communication in one and the same 3-wire cable

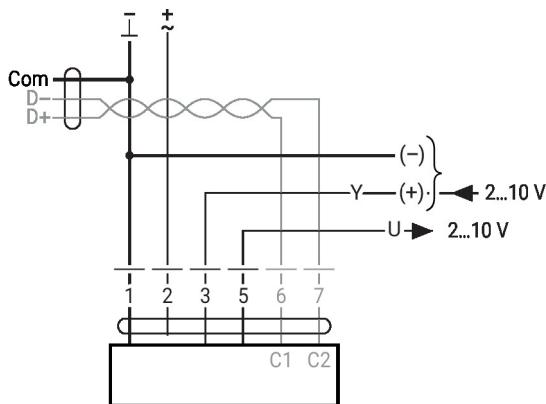
- no shielding or twisting necessary
- no terminating resistors required

## MP-Bus

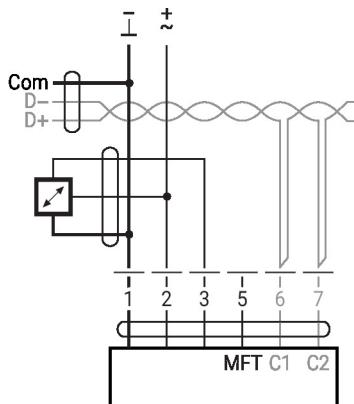


**Further electrical installations****Functions with specific parameters (configuration necessary)**

Modbus RTU / BACnet MS/TP with analogue setpoint (hybrid operation)

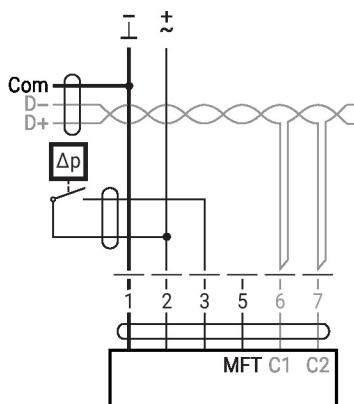
**Sensor connection**

Connection with active sensor, e.g. 0...10 V @ 0...50°C



Possible input voltage range:  
0...10 V  
Resolution 30 mV

Connection with switching contact, e.g. differential pressure switch



Switching contact requirements:  
The switching contact must be able to switch a current of 16 mA at 24 V accurately.  
Start point of the operating range must be configured on the MOD actuator as  $\geq 0.5$  V.



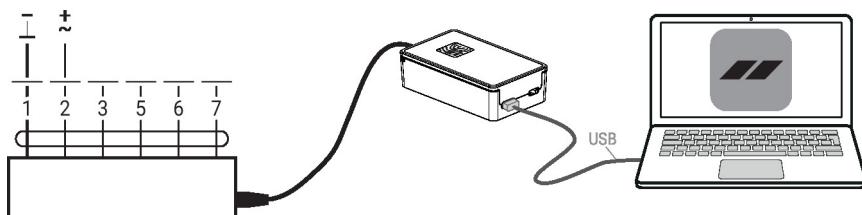
## Service

Using Belimo Assistant 2, device parameters can be modified. Belimo Assistant 2 can operate on a smartphone, tablet or PC. The available connection options vary depending on the hardware on which Belimo Assistant 2 is installed.

For more information about Belimo Assistant 2, refer to the Quick Guide – Belimo Assistant 2.

**Wired connection**

Belimo devices can be accessed by connecting Belimo Assistant Link to the USB port on a PC or laptop and to the Service Socket or MP-Bus wire on the device.

**Quick addressing**

1. Press the "Address" button until the green "Power" LED is no longer illuminated. The green "Power" LED flashes in accordance with the previously set address.

2. Set the address by pressing the "Address" button the corresponding number of times (1...16).

3. The green LED flashes in accordance with the address that has been entered (1...16). If the address is not correct, it can be reset in accordance with step 2.

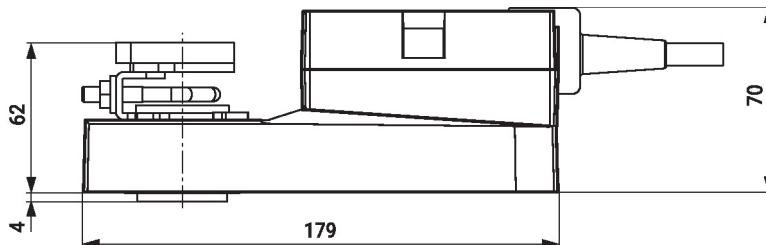
4. Confirm the address setting by pressing the green "Adaptation" button.

If the address is not confirmed within 60 seconds, the address procedure will be ended. Any address change that has already been started will be discarded.

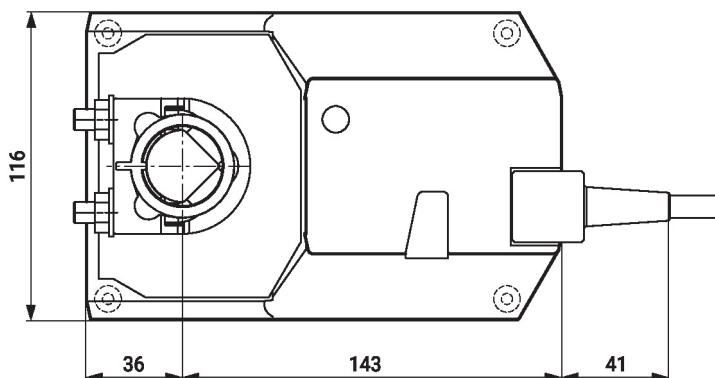
The resulting BACnet MS/TP and Modbus RTU address is made up of the set basic address plus the short address (e.g. 100+7=107).

**Dimensions****Shaft length**

	Min. 52 mm [2.05"]
	Min. 20 mm [0.75"]

**Clamping range**

	12...22	12...18
	22...26.7	12...18



## Further documentation

- Tool connections
- BACnet Interface description
- Modbus Interface description
- Overview MP Cooperation Partners
- MP Glossary
- Introduction to MP-Bus Technology
- Quick Guide – Belimo Assistant 2