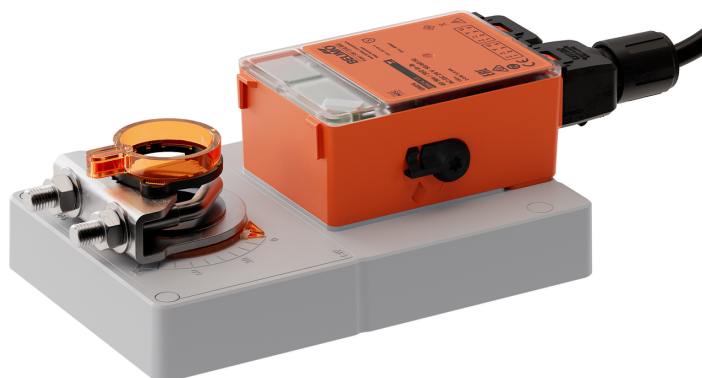


Damper actuator for adjusting dampers in technical building installations

GM24SR

- Torque motor 40 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, Open/close, 3-point, communicative via MP-Bus
- Running time motor 150 s (90...150 s)
- With pluggable connecting cable



Picture may differ from product

## Technical data

<b>Electrical data</b>	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 19.2...28.8 V
	Power consumption in operation	2 W
	Power consumption in rest position	0.2 W
	Power consumption for wire sizing	5 VA
	Connection supply / control	Cable 1 m 4x 0.5 mm <sup>2</sup> [21 AWG], halogen-free
	Parallel operation	See Electrical Installation or contact your local Belimo representative
<b>Data bus communication</b>	Communicative control	MP-Bus
	Number of nodes	MP-Bus max. 16
<b>Functional data</b>	Torque motor	40 Nm
	Operating range Y	2...10 V
	Input impedance	100 kΩ
	Operating range Y variable	Start point 0.5...30 V End point 2.5...32 V
	Operating modes optional	Open/close 3-point communicative
	Position feedback U	2...10 V
	Position feedback U note	Max. 1 mA
	Position feedback U variable	Start point 0.5...8 V End point 2.5...10 V
	Response sensitivity	1.0% of ΔU
	Reversal hysteresis	2.5% of ΔU
	Position accuracy	±5%
	Direction of motion motor	Y = 0 V: left end stop, position CW
	Direction of motion variable	electronically reversible
	Direction of motion note	selectable with Belimo Assistant 2
	Manual override	with lateral lever, can be locked
	Angle of rotation	Max. 95°
	Angle of rotation note	can be electronically limited on both sides with Belimo Assistant 2
	Running time motor	150 s / 90°
	Running time motor variable	90...150 s
	Sound power level, motor	40 dB(A)
	Adaptation setting range	with Belimo Assistant 2

**Technical data**

<b>Functional data</b>	Override control	MIN (minimum position) = 0% MID (intermediate position, AC only) = 50% MAX (maximum position) = 100%
	Override control variable	MIN = 0%...(MAX – 20%) MID = MIN...MAX MAX = (MIN + 20%)...100%
	Mechanical interface	Universal shaft clamp reversible 12...26.7 mm
	Position indication	Mechanical
<b>Safety data</b>	Protection class IEC/EN	III, Protective Extra-Low Voltage (PELV)
	Degree of protection IEC/EN	IP54
	EMC	CE according to 2014/30/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Type of action	Type 1
	Rated impulse voltage supply / control	0.8 kV
	Pollution degree	3
	Environmental conditions operation	Class 3K23 according to IEC 60721-3-3
	Ambient humidity	Max. 95% RH, non-condensing
	Ambient temperature	-30...55°C [-22...131°F]
	Ambient temperature note	up to 60°C [140°F], max. 2 h/day
	Environmental conditions transport	Class 2K11 according to IEC 60721-3-2
	Environmental conditions storage	Class 1K21 according to IEC 60721-3-1
	Storage temperature	-40...80°C [-40...176°F]
	Servicing	maintenance-free
<b>Weight</b>	Weight	1.6 kg

**Safety notes**

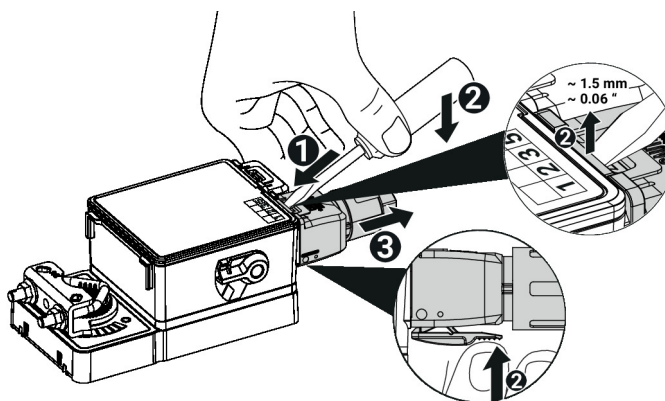

- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section and the design, as well as the installation situation and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

**Product features**

<b>Operating mode</b>	Conventional operation: The actuator is connected with an analogue control signal Y (note the operating range) and drives to the position defined. The measuring voltage U serves for the electrical display of the actuator position and as control signal for other actuators. Operation on Bus: The actuator receives its digital control signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.
<b>Visual status display</b>	The device indicates its operation by means of a green LED.

**Product features**

<b>Converter for sensors</b>	Connection option for an active sensor. The actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher-level system. Additional material may be required for the sensor connection. See "Electrical accessories".
<b>Configurable device</b>	The factory settings cover the most common applications. Parameters can be modified using Belimo Assistant 2, either wirelessly via Near Field Communication (NFC), or via a wired connection.
<b>Simple direct mounting</b>	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation mechanism to prevent the actuator from rotating.
<b>Manual override</b>	Manual override possible with lateral lever (the gear train is disengaged for as long as the lever is actuated or remains locked). Manual override with stationary actuator is used for installation, commissioning and maintenance of the application.
<b>Adjustable angle of rotation</b>	Adjustable angle of rotation with electrical end stops. The setting of the control range (Min - Max) is made with Belimo Assistant 2.
<b>High functional reliability</b>	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
<b>Innovative motorisation</b>	The actuator uses the powerful Belimo M600 microchip in combination with the INFORM method. It provides the full starting torque from a standstill with high precision (sensorless INFORM-Drive by Prof. Schrödl).
<b>Adaptation</b>	An adaptation can be triggered with Belimo Assistant 2. During adaptation of a mounted actuator, both damper end stops on the system are detected (entire setting range). The actuator then moves into the position defined by the control signal.
<b>Connection</b>	The cable can be plugged in and unplugged from the device.


**Accessories**

<b>Tools</b>	<b>Description</b>	<b>Type</b>
	Service tool for wired and wireless setup, on-site operation and troubleshooting.	Belimo Assistant 2
	Belimo Assistant Link Bluetooth and USB to NFC and MP-Bus converter for configurable and communicative devices	LINK.10
	Connecting cable 5 m, A: RJ11 6/4 LINK.10, B: free wire end for connection to MP/PP terminal	ZK2-GEN
<b>Electrical accessories</b>	<b>Description</b>	<b>Type</b>
	Signal converter voltage/current 100 kΩ 4...20 mA, Supply AC/DC 24 V	Z-UIC
	Positioner for wall mounting	SGA24
	Positioner for built-in mounting	SGE24
	Positioner for front-panel mounting	SGF24
	Positioner for wall mounting	CRP24-B1
	Connecting cable 24 V, 1 m FRNC, 4x 0.5 mm <sup>2</sup> /21 AWG	A.EISC.10
	Connecting terminal compl. IP65 24 V	A.EIST.10

**Accessories**
**Mechanical accessories**
**Description**

Cable conduit connector, M20  
Cable conduit connector, 1/2" NPT  
Blanking plug

**Type**

S.EISCC.11  
S.EISCC.10  
S.EISBP.10

**Description**

Actuator arm for standard shaft clamp  
Ball joint suitable for damper crank arm KH8 / KH10  
Damper crank arm Slot width 8.2 mm, clamping range  $\varnothing 14...25$  mm  
Anti-rotation mechanism 230 mm, Multipack 20 pcs.  
Mounting kit for linkage operation for flat installation  
Position indicator

**Type**

AH-GMA  
KG10A  
KH10  
Z-ARS230  
ZG-GMA  
S.MISPI.10

**Electrical installation**


Supply from isolating transformer.

Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.

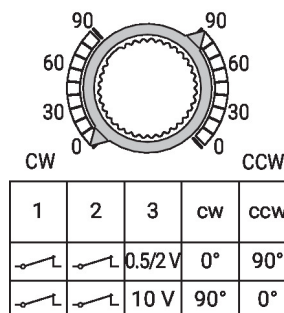
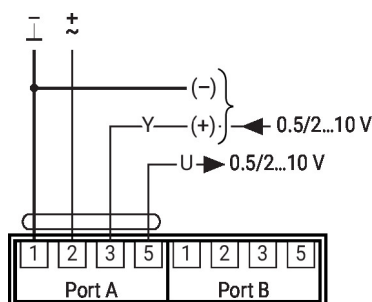
The cable cross-section ( $\text{mm}^2$ ) must be determined on the basis of the actuator performance data (VA, W), the cable resistance, the number of actuators, and the total cable length according to electrotechnical principles. High voltage drops across the installation cables can affect the function of the actuator if, for example, the nominal voltage range (AC/DC) is not respected.

High voltage drops across the control signal and position feedback lines (Y/U) with respect to ground affect the signal values (0.5/2...10 V) and can change the actuator position.

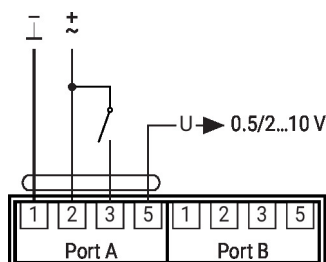
**Wire colours:**

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

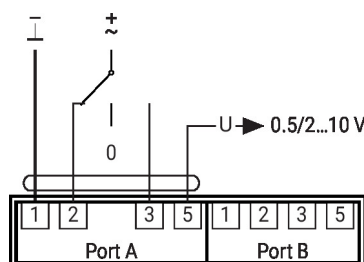
AC/DC 24 V, modulating


**Further electrical installations**
**Hardwired control with specific parameters**

AC/DC 24 V, open/close



AC/DC 24 V, 3-point



## Further electrical installations

### MP-Bus

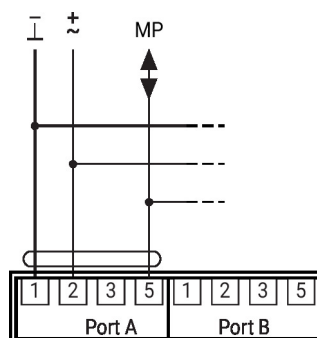
#### MP-Bus network topology



There are no restrictions regarding the network topology (bus, star, ring or mixed forms are permitted).  
Supply and communication in one and the same 3-wire cable

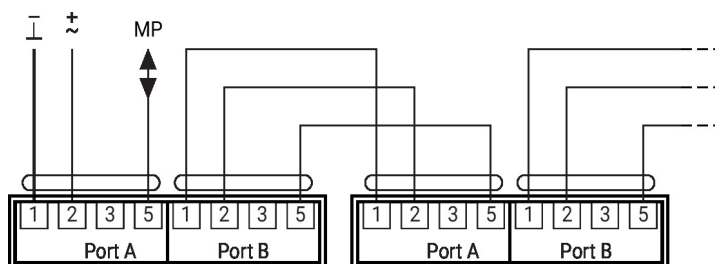
- no shielding or twisting necessary
- no terminating resistors required

#### Connection on the MP-Bus



Max. 16 MP-Bus nodes

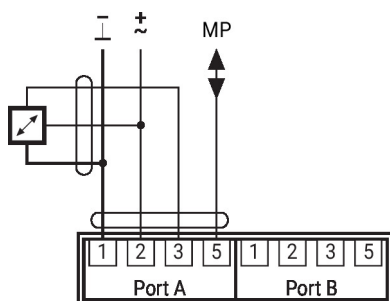
#### Possibility of daisy-chain wiring



Additional material may be required for daisy-chain wiring.  
See "Electrical accessories".

### Sensor connection

#### Connection with active sensor

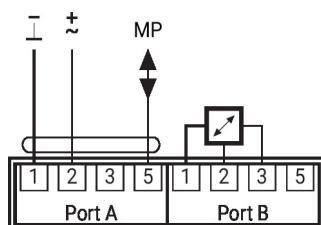


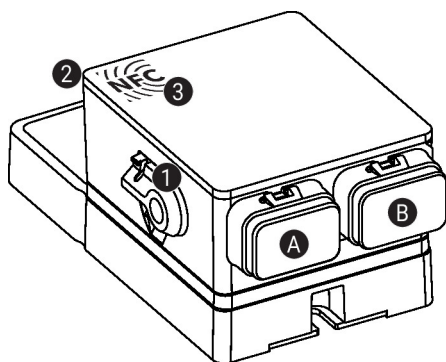
Possible input voltage range:  
0...10 V  
Resolution 10 mV  
To capture for example:

- Active temperature, humidity and air quality sensors
- Pressure / differential pressure sensors

#### Alternative sensor connection

##### Connection with active sensor



**Operating controls and indicators**

**1 Manual override lever**

Rotate lever counterclockwise to end position:

- Gear train disengages, manual override possible

Return lever clockwise to starting position:

- Gear train engages, followed by standard mode

**2 Status display, LED green**

LED on: operation OK

LED flashing: Connect device with Belimo Assistant 2 for additional information

LED off: No power supply

**3 NFC interface**

**A** Port A, see Electrical Installation

**B** Port B, see Electrical Installation

**Service**

Using Belimo Assistant 2, device parameters can be modified. Belimo Assistant 2 can operate on a smartphone, tablet or PC. The available connection options vary depending on the hardware on which Belimo Assistant 2 is installed.

For more information about Belimo Assistant 2, refer to the Quick Guide – Belimo Assistant 2.

**Wireless connection**

Belimo devices marked with the NFC logo can be accessed either directly with an NFC-capable smartphone or with a Bluetooth-capable smartphone connected to Belimo Assistant Link or ZIP-BT-NFC.

Align the NFC-capable smartphone or Belimo Assistant Link with the device's NFC logo so that both NFC antennas are superposed.

