

Communicative rotary actuator for ball valves

- Torque motor 10 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative, hybrid
- Conversion of sensor signals
- Communication via BACnet MS/TP, Modbus RTU, Belimo-MP-Bus or conventional control





NR24A-MOD

## Technical data

Nominal voltage	AC/DC 24 V
Nominal voltage frequency	50/60 Hz
Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
Power consumption in operation	3.5 W
Power consumption in rest position	1.2 W
Power consumption for wire sizing	6 VA
Connection supply / control	Cable 1 m, 6 x 0.75 mm <sup>2</sup>
Communicative control	BACnet MS/TP Modbus RTU (default setting) MP-Bus
Number of nodes	BACnet / Modbus see interface description MP-Bus max. 8
Torque motor	10 Nm
Operating range Y	210 V
Operating range Y variable	0.510 V
Position feedback U	210 V
Position feedback U note	Max. 1 mA
Position feedback U variable	Start point 0.58 V End point 210 V
Position accuracy	±5%
Manual override	with push-button, can be locked
Running time motor	90 s / 90°
Running time motor variable	45170 s
Adaptation setting range	manual (automatic on first power-up)
Adaptation setting range variable	Adaptation when switched on Adaptation after pushing the manual override button
Override control, controllable via bus communication	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position) = 50%
Override control variable	MAX = (MIN + 33%)100% MIN = 0%(MAX – 33%) ZS = MINMAX
Sound power level, motor	45 dB(A)
Position indication	Mechanically, pluggable
Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)
Power source UL	Class 2 Supply
	Class 2 Supply IP54
Power source UL	
	Nominal voltage range Power consumption in operation Power consumption in rest position Power consumption for wire sizing Connection supply / control  Communicative control  Number of nodes  Torque motor Operating range Y Operating range Y Operating range Y variable Position feedback U Position feedback U variable  Position accuracy Manual override Running time motor Running time motor variable  Adaptation setting range Adaptation setting range Adaptation setting range variable  Override control, controllable via bus communication  Override control variable



Technical data sheet	NR24A-MOD	
EMC	CE according to 2014/30/EU	
Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14	
UL Approval	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 The UL marking on the actuator depends on the production site, the device is UL-compliant in any case	
Mode of operation	Type 1	
Rated impulse voltage supply / control	0.8 kV	
Pollution degree	3	
Ambient humidity	Max. 95% RH, non-condensing	
Ambient temperature	-3050°C [-22122°F]	
Storage temperature	-4080°C [-40176°F]	
Servicing	maintenance-free	

## Safety notes



Weight

Weight

Safety data

 This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.

 $0.85 \, \text{kg}$ 

- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or
  aggressive gases interfere directly with the device and that it is ensured that the ambient
  conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The switch for changing the direction of rotation may only be operated by authorised specialists. The direction of rotation must not in particular be reversed in a frost protection circuit.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

## **Product features**

Mode of operation

The actuator is fitted with an integrated interface for BACnet MS/TP, Modbus RTU and MP-Bus. It receives the digital control signal from the control system and returns the current status.

Converter for sensors

Connection option for a sensor (passive, active or with switching contact). In this way, the analogue sensor signal can be easily digitised and transferred to the bus systems: BACnet, Modbus or MP-Bus.

Parametrisable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

The communication parameters of the bus systems (address, baud rate etc.) are set with the ZTH EU. Pressing the "Address" button on the actuator while connecting the supply voltage, resets the communication parameters to the factory setting.

Quick addressing: The BACnet and Modbus address can alternatively be set using the buttons on the actuator and selecting 1...16. The value selected is added to the «Basic address» parameter and results in the effective BACnet and Modbus address.

Combination analogue - communicative (hybrid mode)

With conventional control by means of an analogue control signal, BACnet or Modbus can be used for the communicative position feedback

Simple direct mounting

Straightforward direct mounting on the ball valve with only one central screw. The assembly tool is integrated in the plug-in position indication. The mounting orientation in relation to the ball valve can be selected in 90° steps.



## **Technical data sheet**

NR24A-MOD

Manual override

Manual override with push-button possible (the gear train is disengaged for as long as the

button is pressed or remains locked).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the

end stop is reached.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaptation, which is when the operating range and position feedback adjust

themselves to the mechanical setting range.

The actuator then moves into the position defined by the control signal.

Factory setting: Y2 (counter-clockwise rotation).

Adaptation and synchronisation

An adaptation can be triggered manually by pressing the "Adaptation" button or with the PCTool. Both mechanical end stops are detected during the adaptation (entire setting range).

Automatic synchronisation after pressing the manual override button is configured. The

synchronisation is in the home position (0%).

The actuator then moves into the position defined by the control signal.

A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

#### Accessories

Tools	Description	Туре
	Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH EU
	Belimo PC-Tool, Software for adjustments and diagnostics Adapter for Service-Tool ZTH	MFT-P MFT-C
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN

## **Electrical installation**



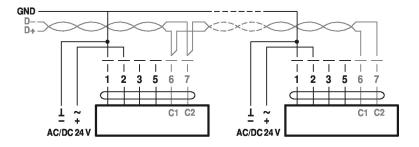
Supply from isolating transformer.

The wiring of the line for BACnet MS/TP / Modbus RTU is to be carried out in accordance with applicable RS-485 regulations.

Modbus / BACnet: Supply and communication are not galvanically isolated. Connect earth signal of the devices with one another.

## Wiring diagrams

BACnet MS/TP / Modbus RTU



#### Cable colours:

1= black

2 = red

3 = white

5 = orange

6 = pink

7 = grey

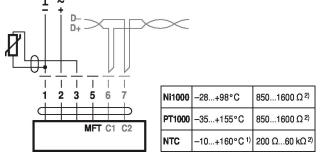
BACnet / Modbus signal

assignment:

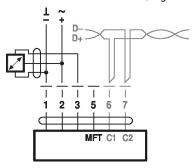
C1 = D - = A

C2 = D + = B

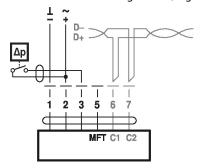
Connection with passive sensor, e.g. Pt1000, Ni1000, NTC



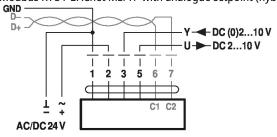
Connection with active sensor, e.g. 0...10 V @ 0...50°C



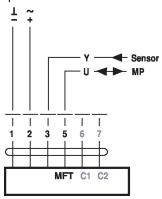
Connection with switching contact, e.g.  $\Delta p$  monitor



Modbus RTU / BACnet MS/TP with analogue setpoint (hybrid mode)



Operation on the MP-Bus



1) depending on type

**Technical data sheet** 

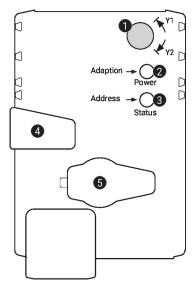
2) Resolution 1 Ohm Compensation of the measured value is recommended

Possible voltage range: 0...32 V (resolution 30 mV)

Requirements for switching contact:
The switching contact must be able to accurately switch a current of 16 mA @ 24 V.



## Operating controls and indicators



Direction of rotation switch

Switch over: Direction of rotation changes

2 Push-button and LED display green

Off: No power supply or malfunction

On: In operation

Flashing: In address mode: Pulses according to set address (1...16)

When starting: Reset to factory setting (Communication)

Press In standard mode: Triggers angle of rotation adaptation button: In address mode: Confirmation of set address (1...16)

3 Push-button and LED display yellow

Off: Standard mode

On: Adaptation or synchronisation process active

or actuator in address mode (LED display green flashing)

Flickering: BACnet / Modbus communication active

Press In operation (>3 s): Switch address mode on and off button: In address mode: Address setting by pressing several times When starting (>5 s): Reset to factory setting (Communication)

4 Manual override button

Press button: Gear train disengages, motor stops, manual override possible

Release button: Gear train engages, standard mode

Service plug

For connecting parametrisation and service tools

Check power supply connection

2 Off and 3 On Possible wiring error in power supply

## Service

## **Quick addressing**

- 1. Press the "Address" button until the green "Power" LED is no longer illuminated. LED flashes in accordance with the previously set address.
- 2. Set the address by pressing the "Address" button the corresponding number of times (1...16).
- 3. The green LED flashes in accordance with the address that has been entered (...16). If the address is not correct, then this can be reset in accordance with Step 2.
- 4. Confirm the address setting by pressing the green "Adaptation" button.

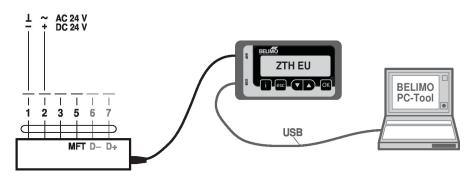
If no confirmation occurs for 60 seconds, then the address procedure is ended. Any address change that has already been started will be discarded.

The resulting BACnet MS/TP and Modbus RTU address is made up of the set basic address plus the short address (e.g. 100+7=107).

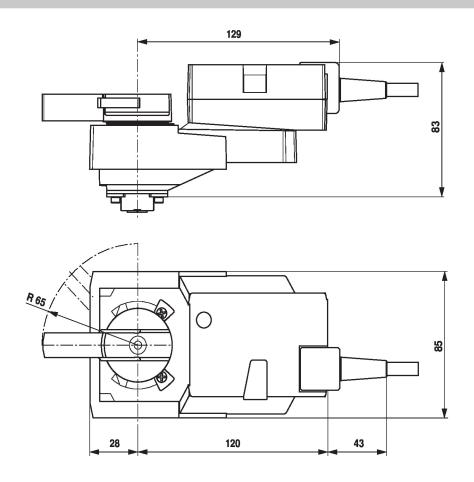


#### **Tools connection**

The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.



## **Dimensions**



# **Further documentation**

- Tool connections
- BACnet Interface description
- Modbus Interface description
- Overview MP Cooperation Partners
- MP Glossary
- Introduction to MP-Bus Technology
- The complete product range for water applications
- Data sheets for ball valves
- Installation instructions for actuators and/or ball valves
- General notes for project planning