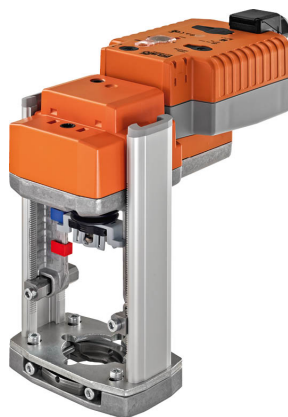


Communicative globe valve actuator with fail-safe for 2-way and 3-way globe valves

- Actuating force 1500 N
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Stroke 20 mm
- Communication via Belimo MP-Bus
- Conversion of sensor signals




## Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	2.5 W
	Power consumption in rest position	1.5 W
	Power consumption for wire sizing	6 VA
	Connection supply / control	Terminals 4 mm <sup>2</sup> (cable ø4...10 mm)
	Parallel operation	Yes (note the performance data)
Data bus communication	Communicative control	MP-Bus
	Number of nodes	MP-Bus max. 8
Functional data	Actuating force motor	1500 N
	Operating range Y	2...10 V
	Input impedance	100 kΩ
	Operating range Y variable	Start point 0.5...30 V End point 2.5...32 V
	Operating modes optional	Open/close 3-point (AC only) Modulating (DC 0...32 V)
	Position feedback U	2...10 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	Start point 0.5...8 V End point 2.5...10 V
	Setting fail-safe position	Stem 0...100%, adjustable (POP rotary knob)
	Bridging time (PF)	2 s
	Bridging time (PF) variable	0...10 s
	Position accuracy	±5%
	Manual override	with push-button
	Stroke	20 mm
	Running time motor	150 s / 20 mm
	Running time motor variable	90...150 s
	Running time fail-safe	35 s / 20 mm
	Sound power level, motor	60 dB(A)
	Sound power level, fail-safe	60 dB(A)
	Adaptation setting range	manual (automatic on first power-up)

## Technical data

Functional data	Adaptation setting range variable	No action Adaptation when switched on Adaptation after pushing the manual override button
	Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%
	Override control variable	MAX = (MIN + 33%)...100% ZS = MIN...MAX
	Position indication	Mechanical, 5...32 mm stroke
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)
	Power source UL	Class 2 Supply
	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Housing	UL Enclosure Type 2
	EMC	CE according to 2014/30/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Type of action	Type 1.AA
	Rated impulse voltage supply / control	0.8 kV
	Pollution degree	3
	Ambient humidity	Max. 95% RH, non-condensing
	Ambient temperature	0...50°C [32...122°F]
	Storage temperature	-40...80°C [-40...176°F]
	Servicing	maintenance-free
Weight	Weight	7.6 kg
Terms	Abbreviations	POP = Power off position / fail-safe position CPO = Controlled power off / controlled fail-safe
		PF = Power fail delay time / bridging time

## Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The switch for changing the direction of motion and so the closing point may be adjusted only by authorised specialists. The direction of motion is critical, particularly in connection with frost protection circuits.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

## Product features

### Operating mode

Conventional operation:

The actuator is connected with a standard control signal of 0...10 V and moves to the position defined by the control signal at the same time as the integrated capacitors are loaded.

Interrupting the supply voltage causes the valve to be moved to the selected fail-safe position by means of stored electrical energy.

Operation on Bus:

The actuator receives its digital control signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

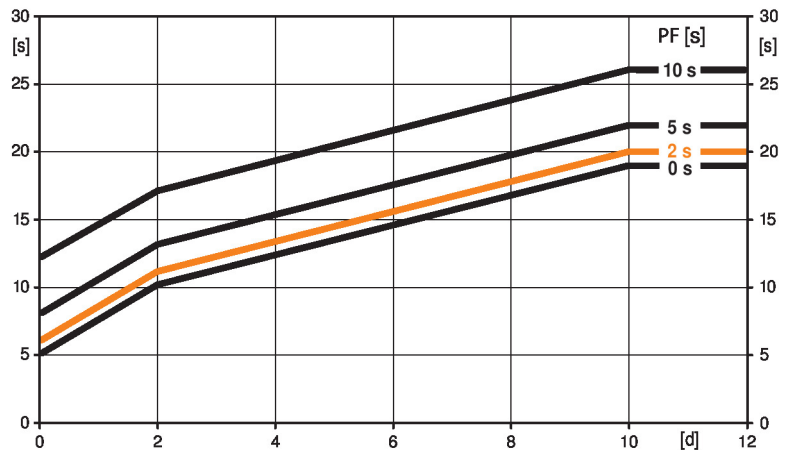
### Pre-charging time (start up)

The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of a power failure, the actuator can move at any time from its current position into the preset fail-safe position.

The duration of the pre-charging time depends mainly on following factors:

- Duration of the power failure
- PF delay time (bridging time)

Typical pre-charging time



[d] = Power failure in days  
[s] = Pre-charging time in seconds  
PF[s] = Bridging time

Calculation example: Given a power failure of 3 days and a bridging time (PF) set at 5 s, the actuator requires a pre-charging time of 14 s after the power has been reconnected (see graphic).

PF [s]	[d]				
	0	1	2	7	≥10
0	5	8	10	15	19
2	6	9	11	16	20
5	8	11	13	18	22
10	12	15	17	22	26
[s]					

### Delivery condition (capacitors)

The actuator is completely discharged after delivery from the factory, which is why the actuator requires approximately 20 s pre-charging time before initial commissioning in order to bring the capacitors up to the required voltage level.

### Bridging time

Power failures can be bridged up to a maximum of 10 s.

In the event of a power failure, the actuator will remain stationary in accordance with the set bridging time. If the power failure is greater than the set bridging time, the actuator will move into the selected fail-safe position.

The bridging time set at the factory is 2 s. It can be modified on site in operation by means of the Belimo service tool MFT-P.

Settings: The rotary knob must not be set to the "Tool" position!

For retroactive adjustments of the bridging time with the Belimo service tool MFT-P or with the ZTH EU adjustment and diagnostic device only the values need to be entered.

## Product features

<b>Setting fail-safe position (POP)</b>	<p>The rotary knob fail-safe position can be used to adjust the desired fail-safe position from 0...100% in 10% increments. The rotary knob refers to the adapted or programmed height of stroke. In the event of a power failure, the actuator will move to the selected fail-safe position, taking into account the bridging time (PF) of 2 s set at the factory.</p> <p>Settings: The rotary knob must be set to the «Tool» position for retroactive settings of the fail-safe position with the Belimo service tool MFT-P. Once the rotary knob is set back to the range 0...100%, the manually set value will have positioning authority.</p>
<b>Converter for sensors</b>	<p>Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.</p>
<b>Parametrisable actuators</b>	<p>The factory settings cover the most common applications. Single parameters can be modified with Belimo Assistant 2 or ZTH EU.</p>
<b>Mounting on third-party valves</b>	<p>The RetroFIT+ actuators for installation on a wide range of valves from various manufacturers are comprised of an actuator, universal valve neck adapter and universal valve stem adapter. Adapt the valve neck and valve stem to begin with, then attach the RetroFIT+ actuator to the valve neck adapter, connect to the valve and start up. The valve neck adapter/actuator can be rotated by 360° on the valve neck, provided the size of the installed valve permits.</p>
<b>Mounting on Belimo valves</b>	<p>Use standard actuators from Belimo for mounting on Belimo globe valves. The installation of RetroFIT+ actuators on Belimo globe valves is technically possible.</p>
<b>Manual override</b>	<p>Manual control with push-button possible - temporary. The gear train is disengaged and the actuator decoupled for as long as the button is pressed.</p> <p>The stroke can be adjusted by using a hexagon socket screw key (5 mm), which is inserted into the top of the actuator. The stem extends when the key is rotated clockwise.</p>
<b>High functional reliability</b>	<p>The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.</p>
<b>Home position</b>	<p>Factory setting: Actuator stem is retracted.</p> <p>The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaptation, which is when the operating range and position feedback adjust themselves to the mechanical setting range.</p> <p>The actuator then moves into the position defined by the control signal.</p>
<b>Adaptation and synchronisation</b>	<p>An adaptation can be triggered manually by pressing the "Adaptation" button or with Belimo Assistant 2. Both mechanical end stops are detected during the adaptation (entire setting range).</p> <p>Automatic synchronisation after pressing the manual override button is parametrised. The synchronisation is in the home position (0%).</p> <p>The actuator then moves into the position defined by the control signal.</p> <p>A range of settings can be made using Belimo Assistant 2.</p>
<b>Setting direction of motion</b>	<p>When actuated, the direction-of-stroke switch changes the direction of motion in normal operation. The direction-of-stroke switch has no influence on the fail-safe position that has been set.</p>

## Accessories

Tools	Description	Type
	Service tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH EU
	Service tool for wired and wireless setup, on-site operation, and troubleshooting.	Belimo Assistant 2
	Adapter for Service-Tool ZTH	MFT-C

## Accessories

	Description	Type
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
Electrical accessories	Description	Type
	Auxiliary switch 2x SPDT add-on	S2A-H
	MP-Bus power supply for MP actuators	ZN230-24MP
Gateways	Description	Type
	Gateway MP to BACnet MS/TP	UK24BAC
	Gateway MP to Modbus RTU	UK24MOD

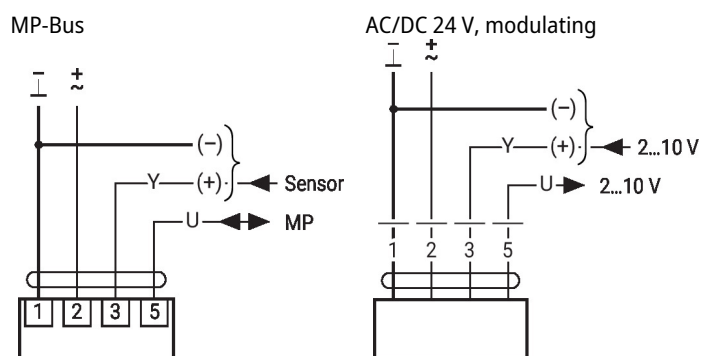
## Electrical installation



Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

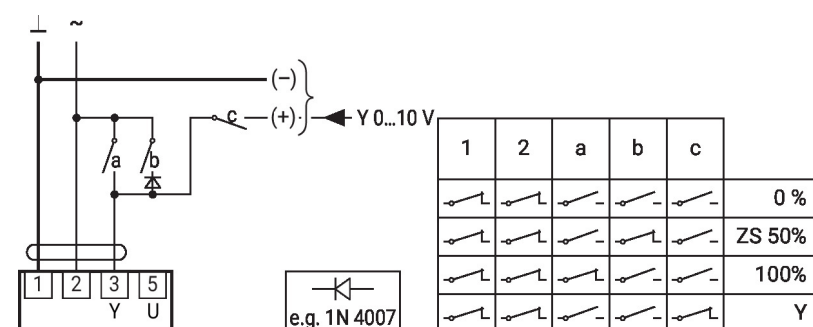
Direction of stroke switch factory setting: Actuator stem retracted (▲).



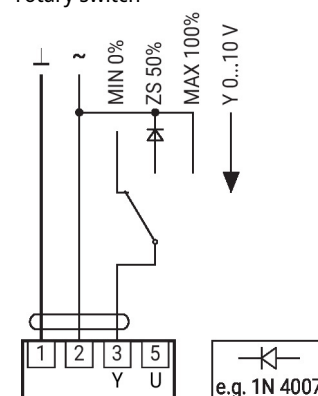
## Further electrical installations

### Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts



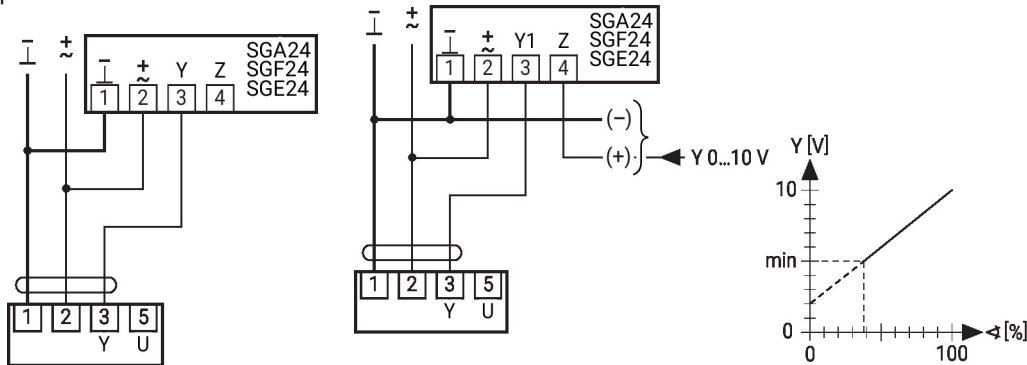
Override control with AC 24 V with rotary switch



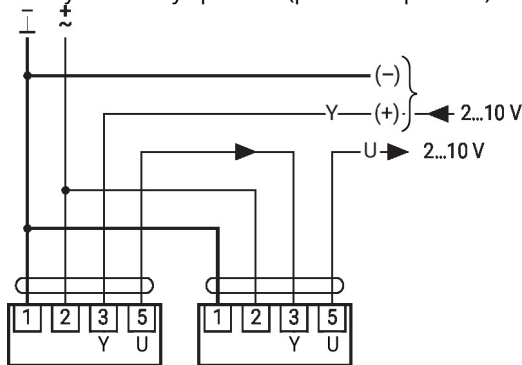
### Functions with basic values (conventional mode)

Control remotely 0...100% with positioner SG..

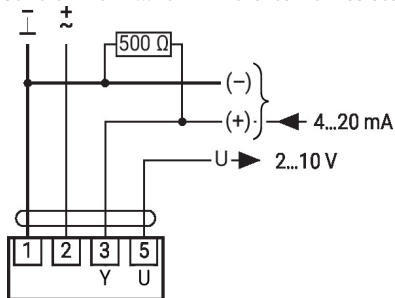
Minimum limit with positioner SG..



### Primary/secondary operation (position-dependent)



### Control with 4...20 mA via external resistor

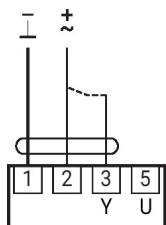


### Caution:

The operating range must be set to DC 2...10 V.

The 500 Ohm resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V.

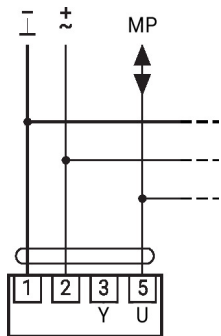
### Functional check



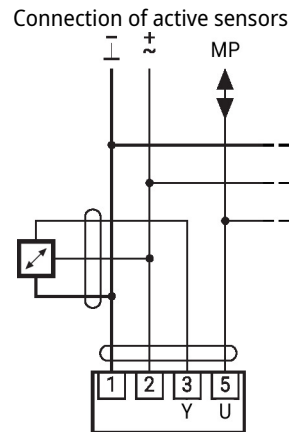
### Procedure

1. Connect 24 V to connections 1 and 2
2. Disconnect connection 3:
  - with direction of rotation L: Actuator rotates to the left
  - with direction of rotation R: Actuator rotates to the right
3. Short-circuit connections 2 and 3:
  - Actuator runs in opposite direction

## MP-Bus



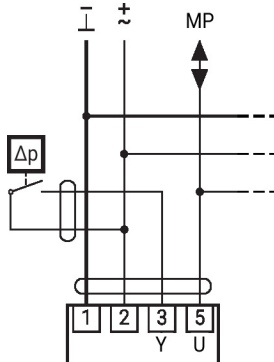
Max. 8 additional MP-Bus nodes



Max. 8 additional MP-Bus nodes

- Supply AC/DC 24 V
- Output signal 0...10 V (max. 0...32 V)
- Resolution 30 mV

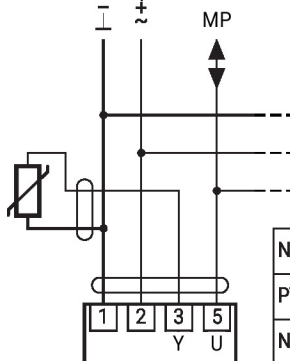
## Connection of external switching contact



Max. 8 additional MP-Bus nodes

- Switching current 16 mA @ 24 V
- Start point of the operating range must be parametrised on the MP actuator as  $\geq 0.5$  V

## Connection of passive sensors



Ni1000	-28...+98°C	850...1600 $\Omega$ <sup>2)</sup>
PT1000	-35...+155°C	850...1600 $\Omega$ <sup>2)</sup>
NTC	-10...+160°C <sup>1)</sup>	200 $\Omega$ ...60 k $\Omega$ <sup>2)</sup>

1) Depending on the type

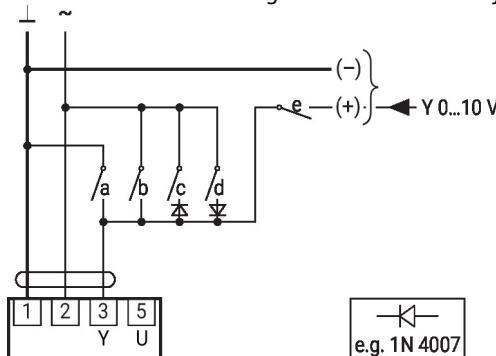
2) Resolution 1 Ohm

Compensation of the measured value is recommended

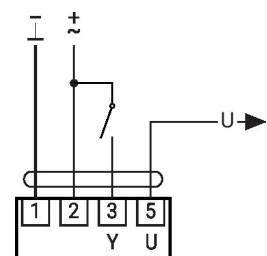
## Functions with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts

Control open/close



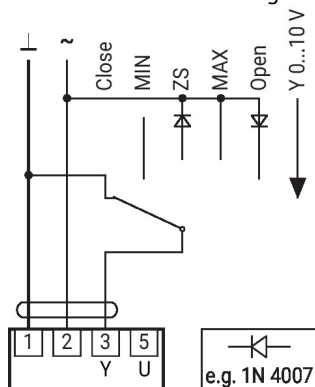
1	2	a	b	c	d	e	
							Close <sup>1)</sup>
							MIN
							ZS
							MAX
							Open
							Y



## Further electrical installations

### Functions with specific parameters (Parametrisation necessary)

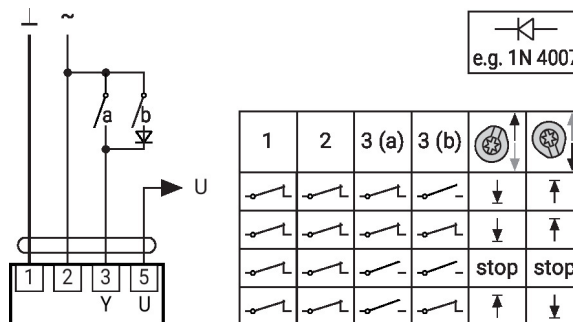
Override control and limiting with AC 24 V with rotary switch



#### Caution:

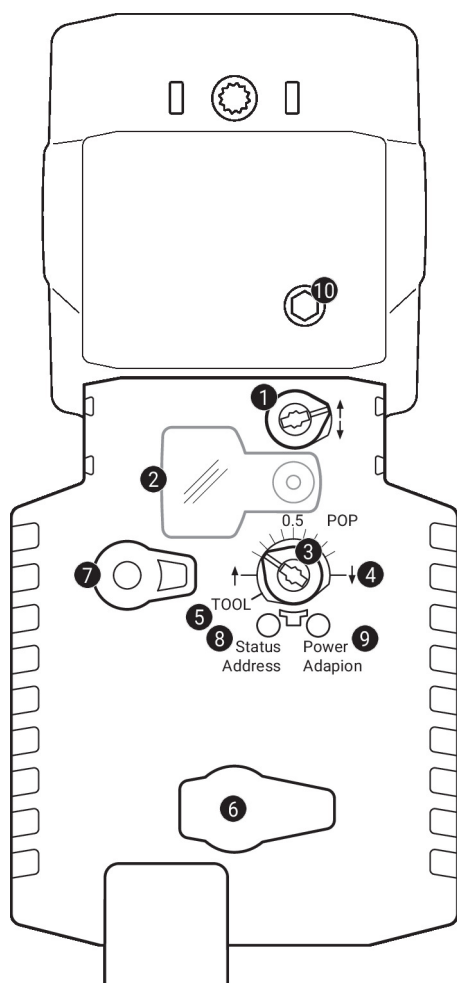
The "Close" function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

Control 3-point with AC 24 V





## Operating controls and indicators



### 1 Direction of stroke switch

Switch over: Direction of stroke changes

### 2 Cover, POP button

### 3 POP button

### 4 Scale for manual adjustment

### 5 Position for adjustment with tool

### 6 Service plug

For connecting parametrisation and service tools

### 7 Manual override button

Press button: Gear train disengages, motor stops, manual override possible

Release button: Gear train engages, standard mode

### 8 Push-button (LED yellow)

Press button: Acknowledgment of addressing

### 9 Push-button (LED green)

Press button: Triggers stroke adaptation, followed by standard mode

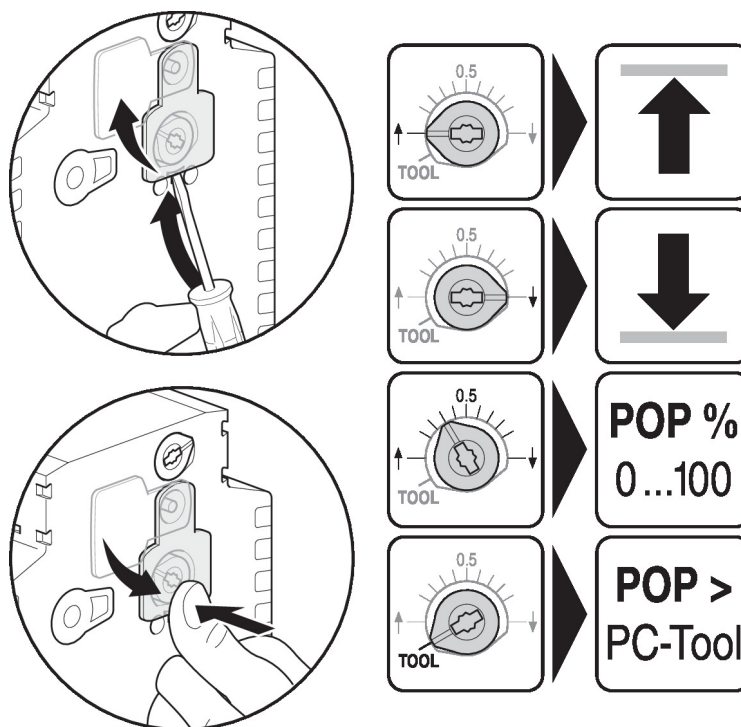
### 10 Manual override

Clockwise: Actuator stem extends

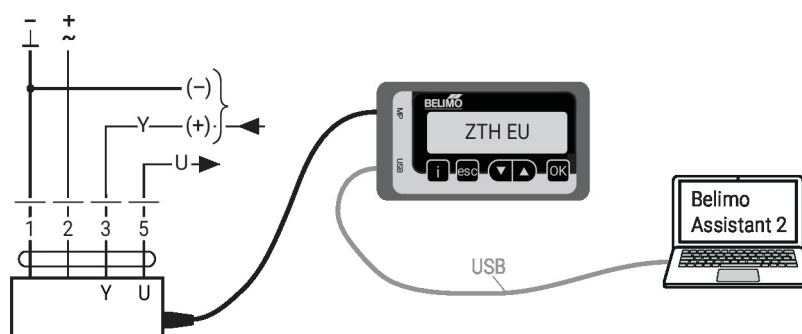
Counterclockwise: Actuator stem retracts

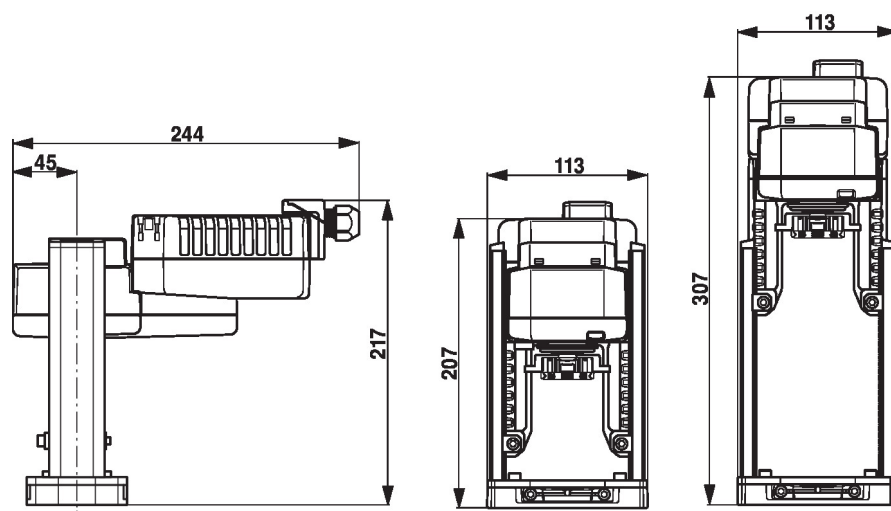
### LED displays

yellow 8	green 9	Meaning / function
Off	On	Operation OK
Off	Flashing	POP function active
On	Off	Fault
Off	Off	Not in operation
On	On	Adaptation process active
Flickering	On	MP-Bus communication active

**Operating controls and indicators**
**Setting fail-safe position (POP)**

**Service**

**Wired connection** The device can be parametrised by ZTH EU via the service socket.  
For an extended parametrisation, Belimo Assistant 2 can be connected.

**Connection ZTH EU / Belimo Assistant 2**


**Dimensions**

**Further documentation**

- Tool connections
- Introduction to MP-Bus Technology
- Overview MP Cooperation Partners
- Data sheets for globe valves
- Installation instructions for actuators
- Quick Guide – Belimo Assistant 2