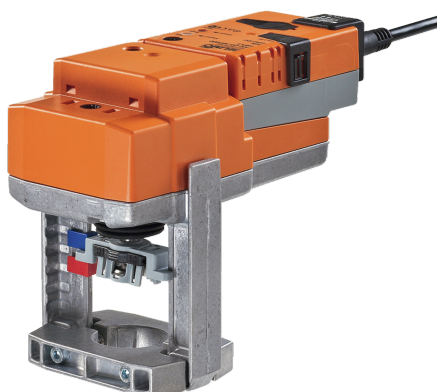


Communicative globe valve actuator for 2-way and 3-way globe valves

- Actuating force 1000 N
- Nominal voltage AC/DC 24 V
- Control modulating, communicative, hybrid, Cloud
- Stroke 20 mm
- Communication via BACnet/IP, Modbus TCP and Cloud
- Ethernet 10/100 Mbit/s, TCP/IP, integrated web server
- Conversion of sensor signals



Picture may differ from product



Technical data

| | | |
|------------------------|--|--|
| Electrical data | Nominal voltage | AC/DC 24 V |
| | Nominal voltage frequency | 50/60 Hz |
| | Nominal voltage range | AC 19.2...28.8 V / DC 21.6...28.8 V |
| | Power consumption in operation | 1.5 W |
| | Power consumption in rest position | 0.5 W |
| | Power consumption for wire sizing | 3 VA |
| | Connection supply / control | Cable 1 m, 6x 0.5 mm ² |
| | Connection Ethernet | RJ45 socket |
| | Parallel operation | Yes (note the performance data) |
| Data bus communication | Communicative control | Cloud BACnet/IP Modbus TCP |
| | Number of nodes | BACnet / Modbus see interface description |
| Functional data | Actuating force motor | 1000 N |
| | Operating range Y | 2...10 V |
| | Input impedance | 34 kΩ |
| | Operating range Y variable | 0.5...10 V |
| | Position accuracy | ±5% |
| | Manual override | with push-button, can be locked |
| | Stroke | 20 mm |
| | Running time motor | 150 s / 20 mm |
| | Running time motor variable | 90...150 s |
| | Sound power level, motor | 45 dB(A) |
| | Adaptation setting range | manual (automatic on first power-up) |
| | Position indication | Mechanical, 5...20 mm stroke |
| Safety data | Protection class IEC/EN | III, Safety Extra-Low Voltage (SELV) |
| | Degree of protection IEC/EN | IP40 IP54 when using protective cap or protective grommet for RJ45 socket |
| | EMC | CE according to 2014/30/EU |
| | Type of action | Type 1 |
| | Rated impulse voltage supply / control | 0.8 kV |
| | Pollution degree | 3 |
| | Ambient humidity | Max. 95% RH, non-condensing |
| | Ambient temperature | -30...50°C [-22...122°F] |

| | | |
|--------------------|---------------------|--------------------------|
| Safety data | Storage temperature | -40...80°C [-40...176°F] |
| | Servicing | maintenance-free |
| Weight | Weight | 1.2 kg |

Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The switch for changing the direction of motion and so the closing point may be adjusted only by authorised specialists. The direction of motion is critical, particularly in connection with frost protection circuits.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Operating mode The actuator is controlled via the Cloud, BACnet/IP or Modbus TCP and drives to the position defined by the control signal. Various data points can be written and read via the same interfaces.

Hybrid mode:

The actuator receives its analogue control signal from the higher-level controller and drives to the position defined. Using the Cloud, BACnet/IP or Modbus TCP, various data points can be read and, with the exception of the control signal, written.

Converter for sensors Connection option for two sensors (passive sensor, active sensor or switching contact). The actuator serves as an analogue/digital converter for the transmission of the sensor signal to the higher level system.

Communication The configuration can be carried out through the integrated web server (RJ45 connection to the web browser), by communicative means or via the Cloud.

Additional information regarding the integrated web server can be found in the separate documentation.

"Peer to Peer" connection

<http://belimo.local:8080>

The Notebook must be set to "DHCP".
Make sure that only one network connection is active.

Standard IP address:

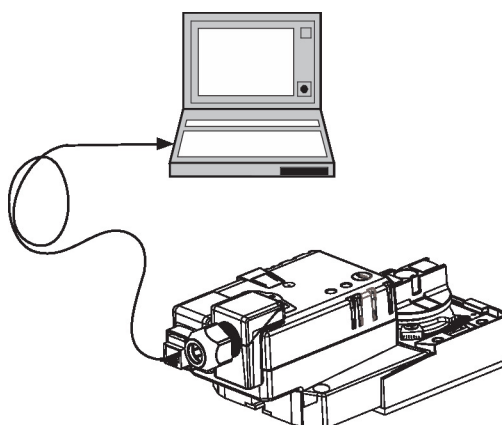
<http://192.168.0.10:8080>

Static IP address

Password (read-only):

User name: «guest»

Password: «guest»



Product features

| | |
|---------------------------------------|--|
| Simple direct mounting | Simple direct mounting on the globe valve by means of form-fit hollow clamping jaws. The actuator can be rotated by 360° on the valve neck. |
| Data recording | The recorded data (integrated data recording for 13 months) can be used for analytical purposes. Download csv files via web browser. |
| Manual override | Manual override with push-button possible (the gear train is disengaged for as long as the button is pressed or remains locked). The stroke can be adjusted by using a hexagon socket screw key (4 mm), which is inserted into the top of the actuator. The stroke shaft extends when the key is rotated clockwise. |
| High functional reliability | The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached. |
| Position indication | The stroke is indicated mechanically on the bracket with tabs. The stroke range adjusts itself automatically during operation. |
| Home position | Factory setting: Actuator stem is retracted. When valve-actuator combinations are shipped, the direction of motion is set in accordance with the closing point of the valve. The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaptation, which is when the operating range and position feedback adjust themselves to the mechanical setting range. The actuator then moves into the position defined by the control signal. |
| Adaptation and synchronisation | An adaptation can be triggered manually by pressing the "Adaptation" button. Both mechanical end stops are detected during the adaptation (entire setting range). The actuator then moves into the position defined by the control signal. |
| Setting direction of motion | When actuated, the direction-of-stroke switch changes the direction of motion in normal operation. |

Accessories

| Tools | Description | Type |
|------------------------|---|----------|
| | Service tool, with ZIP-USB function, for configurable and communicative Belimo actuators, VAV controller and HVAC performance devices | ZTH EU |
| | Connecting cable 5 m, A: RJ11 6/4 LINK.10, B: 6-pin for connection to service socket | ZK1-GEN |
| | Belimo Assistant Link Bluetooth and USB to NFC and MP-Bus converter for configurable and communicative devices | LINK.10 |
| Electrical accessories | Description | Type |
| | Grommet for RJ connection module, Multipack 50 pcs. | Z-STRJ.1 |
| | Stem heater for LV., NV., SV.. actuator | ZH24-1-A |

Electrical installation



Supply from isolating transformer.

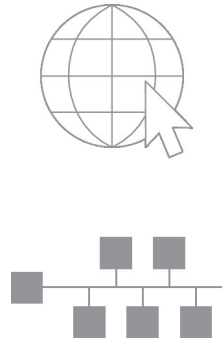
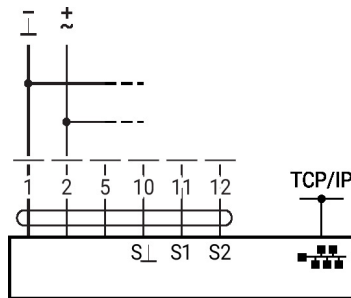
Direction of stroke switch factory setting: Actuator stem retracted (▲).

Electrical installation

Wire colours:

- 1 = black
- 2 = red
- 5 = orange
- 10 = yellow/black
- 11 = yellow/pink
- 12 = yellow/grey

AC/DC 24 V



Optional connection via RJ45
(direct connection to notebook /
connection via Intranet or
Internet) for access to the
integrated web server

Further electrical installations



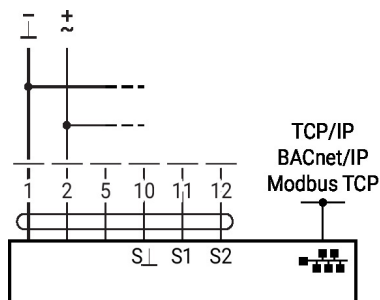
The connection diagrams shows connections for the first sensor on terminal S1, while the second sensor can be connected identically on terminal S2.

Parallel use of different sensor types is permitted.

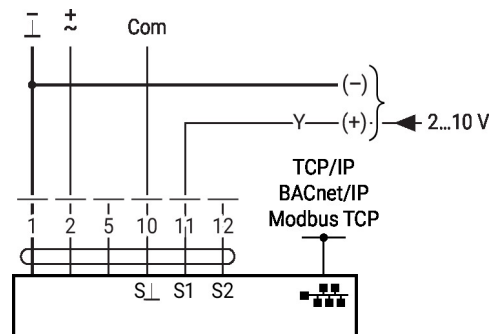
For hybrid operation, S1 is used for the control signal Y and must be configured as an active sensor.

Functions with specific parameters (configuration necessary)

TCP/IP (Cloud) / BACnet/IP / Modbus TCP

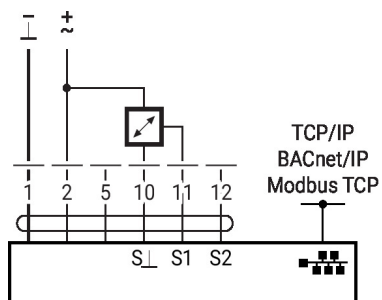


TCP/IP (Cloud) / BACnet/IP / Modbus TCP with analogue setpoint
(hybrid operation)

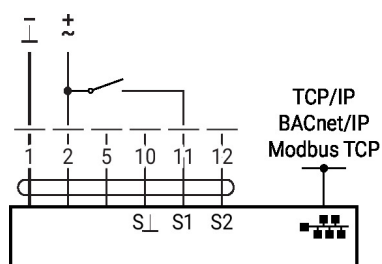


Further electrical installations
Sensor connection

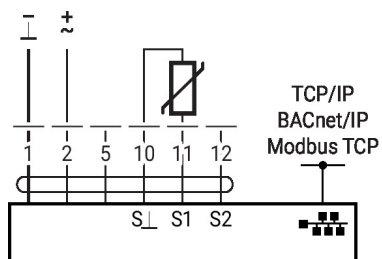
Connection of active sensors



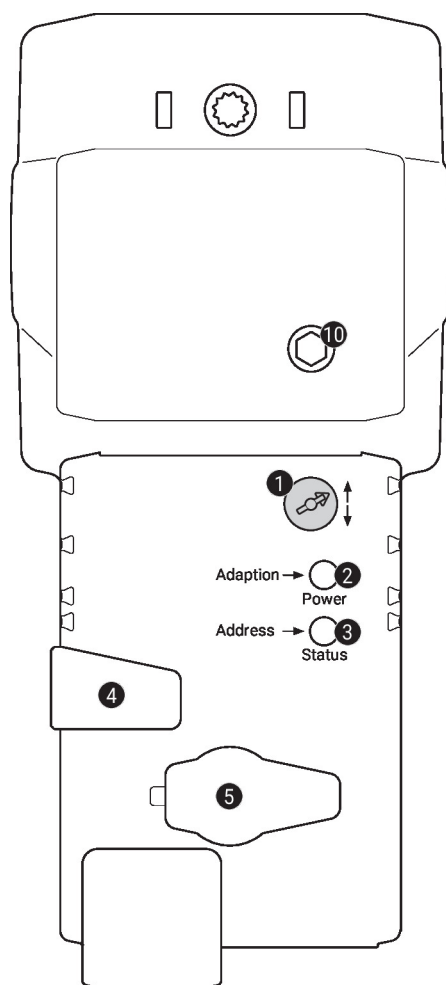
Switching contact connection



Connection of passive sensors



Operating controls and indicators



1 Direction-of-stroke switch

Switch over: Direction of stroke changes

2 Push-button and LED display green

Off: No power supply or malfunction

On: In operation

Flashing: In address mode: Pulses according to set address (1...16)
When starting: Reset to factory setting (Communication)

Press button: In standard mode: Triggers stroke adaptation
In address mode: Confirmation of set address (1...16)

3 Push-button and LED display yellow

Off: Standard mode

On: Adaptation or synchronisation process active
or actuator in address mode (LED display green flashing)

Flickering: BACnet / Modbus communication active

Press button: In operation (>3 s): Switch address mode on and off
In address mode: Address setting by pressing several times
When starting (>5 s): Reset to factory setting (Communication)

4 Manual override button

Press button: Gear train disengages, motor stops, manual override possible

Release button: Gear train engages, standard mode

5 Service plug

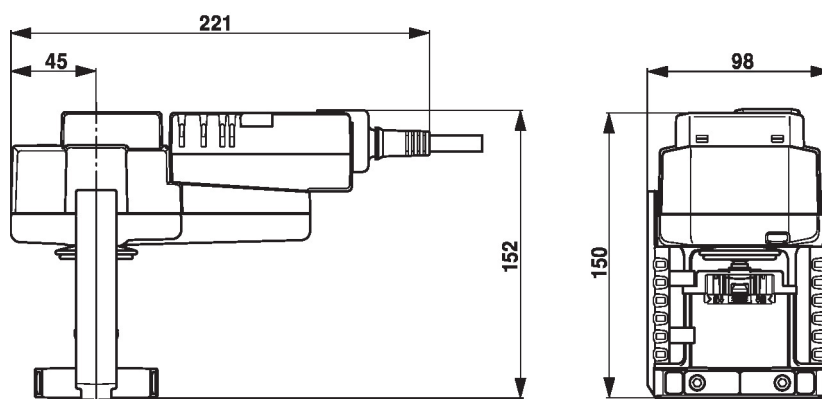
For connecting configuration and service tools

10 Manual override

Clockwise: Actuator stem extends

Counterclockwise: Actuator stem retracts

Dimensions



Further documentation

- General notes for project planning
- Instruction Webserver
- BACnet Interface description
- Modbus Interface description
- Description clientAPI