BELIMO

Technical data sheet GKX24-MFT-T N4

Customizable Fail-Safe multifunction technology actuator for controlling dampers in typical commercial HVAC applications.

- **Torque motor 360 in-lb [40 Nm]**
- **Nominal voltage AC/DC 24 V**
- **Control MFT/programmable**
- **Position feedback 2...10 V**
- **NEMA 4X**

5-year warranty

MFT

Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	11 W
	Power consumption in rest position	3 W
	Transformer sizing	21 VA
	Electrical Connection	Screw terminal (for 26 to 14 GA wire), 1/2" conduit connector
	Overload Protection	electronic throughout 0...95° rotation
	Electrical Protection	actuators are double insulated
Functional data	Torque motor	360 in-lb [40 Nm]
	Operating range Y	2...10 V
	Operating range Y note	4...20 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)
	Input impedance	100 kΩ for 2...10 V (0.1 mA), 500 Ω for 4...20 mA, 1500 Ω for PWM, On/Off and Floating point
	Operating range Y variable	Start point 0.5...30 V End point 2.5...32 V
	Operating modes optional	variable (VDC, PWM, on/off, floating point)
	Position feedback U	2...10 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	VDC variable
	Setting Fail-Safe Position	adjustable with dial or tool 0...100% in 10% increments
	Bridging time (PF)	2 s
	Bridging time (PF) variable	0...10 s
	Pre-charging time	5...26 s
	Direction of motion motor	selectable with switch 0/1
	Direction of motion fail-safe	reversible with switch
	Manual override	external push button
	Angle of rotation	Max. 95°
	Angle of rotation note	adjustable with mechanical stop
	Running Time (Motor)	150 s / 90°
	Running time motor variable	90...150 s
	Running time fail-safe	<35 s
	Adaptation Setting Range	off (default)
	Override control	MIN (minimum position) = 0% MID (intermediate position) = 50% MAX (maximum position) = 100%
	Noise level, motor	52 dB(A)
	Noise level, fail-safe	61 dB(A)

Functional data	Position indication	Mechanical, 5...20 mm stroke
Safety data	Power source UL	Class 2 Supply
	Degree of protection IEC/EN	IP66
	Degree of protection NEMA/UL	NEMA 4X
	Enclosure	UL Enclosure Type 4X
	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1, CSA C22.2 No 24-93, CE acc. to 89/336/EC
	Quality Standard	ISO 9001
	Ambient humidity	Max. 100% RH
	Ambient temperature	-22...122°F [-30...50°C]
	Ambient temperature note	-40...50°C for actuator with integrated heating
	Storage temperature	-40...176°F [-40...80°C]
	Servicing	maintenance-free
Weight	Weight	7.6 lb [3.5 kg]
Materials	Housing material	Polycarbonate

Footnotes

*Variable when configured with MFT options.

†Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 4.

Product features

Default/Configuration

Default parameters for 2 to 10 VDC applications of the GK..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. A feedback signal is provided for position indication or primary and secondary applications. Maximum of two GK's can be piggybacked for torque loads of up to 720 in-lbs. Minimum 1" diameter shaft and primary and secondary wiring.

Operation

The GK..24-MFT-T N4 provides 95° of rotation and a visual indicator shows the position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged by pressing the button located on the actuator cover. The GK..24-MFT-T N4 actuator uses a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in a holding mode. The actuator is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement. Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.

Fail-Safe Indication

LED status indicator lights sequence:

Yellow off / Green on: operation ok, no faults

Yellow off / Green blinking: fail-safe mechanism is active

Yellow on / Green off: fault is detected

Yellow off / Green off: not in operation / capacitors charging

Yellow on / Green on: adaption running

Yellow blinking / Green on: communication with programming tool

Installation Note: Use suitable flexible metallic conduit or its equivalent with the conduit fitting. Not suitable for plenum applications.

For low ambient temperatures, the optional supplemental (-H) Heater add-on is available.

Typical specification

Modulating control, electrical fail-safe damper actuators shall be electronic direct-coupled type, which require no crank arm and linkage and be capable of direct mounting to shaft up to 1.05" diameter. Actuators must provide modulating damper control response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback or primary and secondary applications. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Bridging time

Power failures can be bridged up to a maximum of 10 s.

In the event of a power failure, the actuator will remain stationary in accordance with the set bridging time. If the power failure is greater than the set bridging time, the actuator will move into the selected fail-safe position.

The bridging time set at the factory is 2 s. It can be modified on site in operation by means of the Belimo service tool MFT-P.

Settings: The rotary knob must not be set to the "PROG FAIL-SAFE" position!

For retroactive adjustments of the bridging time with the Belimo service tool MFT-P or with the ZTH EU adjustment and diagnostic device only the values need to be entered.

Factory settings

Default parameters for 2 to 10 VDC applications of the GK..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Accessories

Electrical accessories

Description	Type
Gasket for cable gland (NEMA 4 models)	11097-00001
Cable Gland (NEMA 4 models)	43442-00001
DC Voltage Input Rescaling Module	IRM-100
Feedback potentiometer 10 kΩ add-on, grey	P10000A GR
Feedback potentiometer 1 kΩ add-on, grey	P1000A GR
Feedback potentiometer 140 Ω add-on, grey	P140A GR
Feedback potentiometer 2.8 kΩ add-on, grey	P2800A GR
Auxiliary switch, mercury-free	P475
Auxiliary switch, mercury-free	P475-1
Feedback potentiometer 5 kΩ add-on, grey	P5000A GR
Feedback potentiometer 500 Ω add-on, grey	P500A GR
Convert Pulse Width Modulated Signal to a 2...10 V Signal for Belimo Proportional Actuators	PTA-250
Auxiliary switch 1 x SPDT add-on	S1A
Auxiliary switch 2 x SPDT add-on	S2A
Positioner for wall mounting	SGA24
Positioner for front-panel mounting	SGF24
Gateway MP to BACnet MS/TP	UK24BAC
Resistor, 500 Ω, 1/4" wire resistor with 6" pigtail wires	ZG-R01
Resistor kit, 50% voltage divider	ZG-R02
Transformer, AC 120 V to AC 24 V, 40 VA	ZG-X40

Mechanical accessories

Description	Type
Shaft extension 240 mm ø20 mm for damper shaft ø8...22.7 mm	AV8-25
Wrench 0.512 in. [13 mm]	TOOL-07
1" diameter jackshaft adaptor (11" L).	ZG-JSA-1
1-5/16" diameter jackshaft adaptor (12" L).	ZG-JSA-2
1.05" diameter jackshaft adaptor (12" L).	ZG-JSA-3
Anti-rotation bracket EFB(X)/GKB(X)/GMB(X).	EF-P
Jackshaft mounting bracket.	ZG-120

Tools	Description	Type
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Gateway MP to LonWorks	UK24LON
	Gateway MP to Modbus RTU	UK24MOD
	Connecting cable 16 ft [5 m], A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
	Connecting cable 16 ft [5 m], A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
	Connecting cable 10 ft [3 m], A: RJ11 6/4 ZTH EU, B: 3-pin Weidmüller and supply connection	ZK4-GEN
	Service Tool, with ZIP-USB function, for programmable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH US

Factory add-on option only	Description	Type
	Heater, with adjustable thermostat	N4 Heater Add-on 24V (-H)

Electrical installation

Warning! Live electrical components!
During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

Meets cULus requirements without the need of an electrical ground connection.

1 Provide overload protection and disconnect as required.

3 Actuators may also be powered by DC 24 V.

5 Only connect common to negative (-) leg of control circuits.

7 A 500 Ω resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.

8 Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 V line.

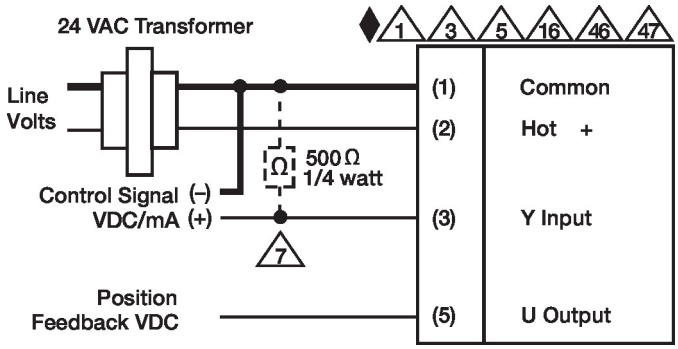
10 For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.

12 IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).

16 Actuators are provided with a numbered screw terminal strip instead of a cable.

46 Actuators may be controlled in parallel. Current draw and input impedance must be observed.

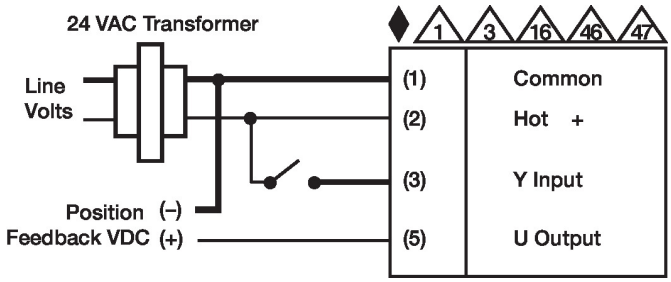
47 Master-Slave wiring required for piggy-back applications. Feedback from Master to control input(s) of Slave(s).



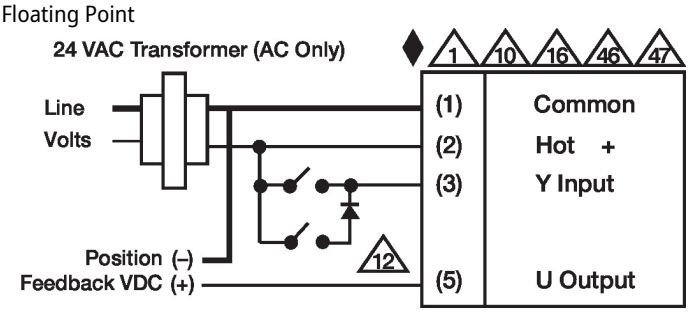
VDC/mA Control

Wiring diagrams

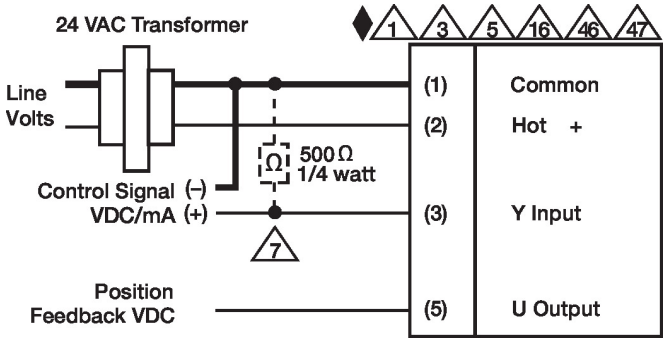
On/Off



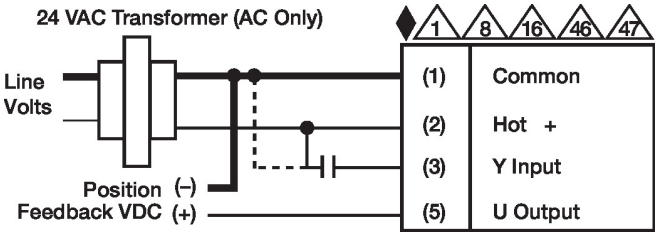
Floating Point



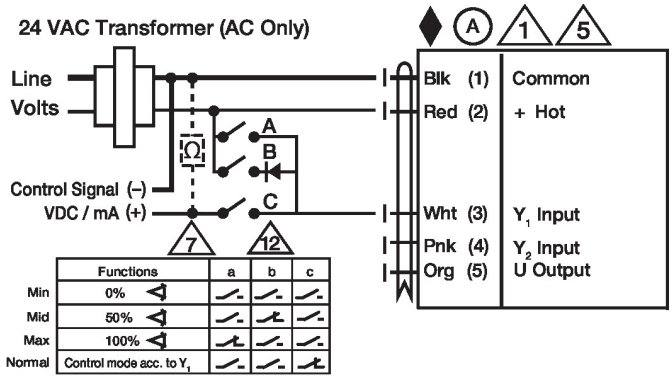
VDC/mA Control



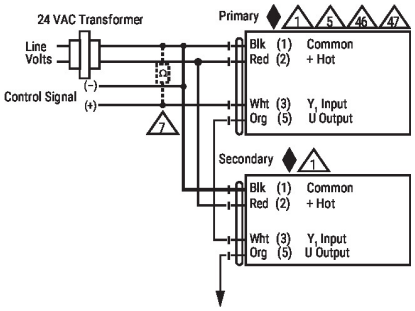
PWM Control



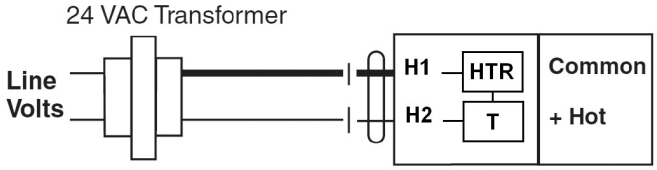
Override Control



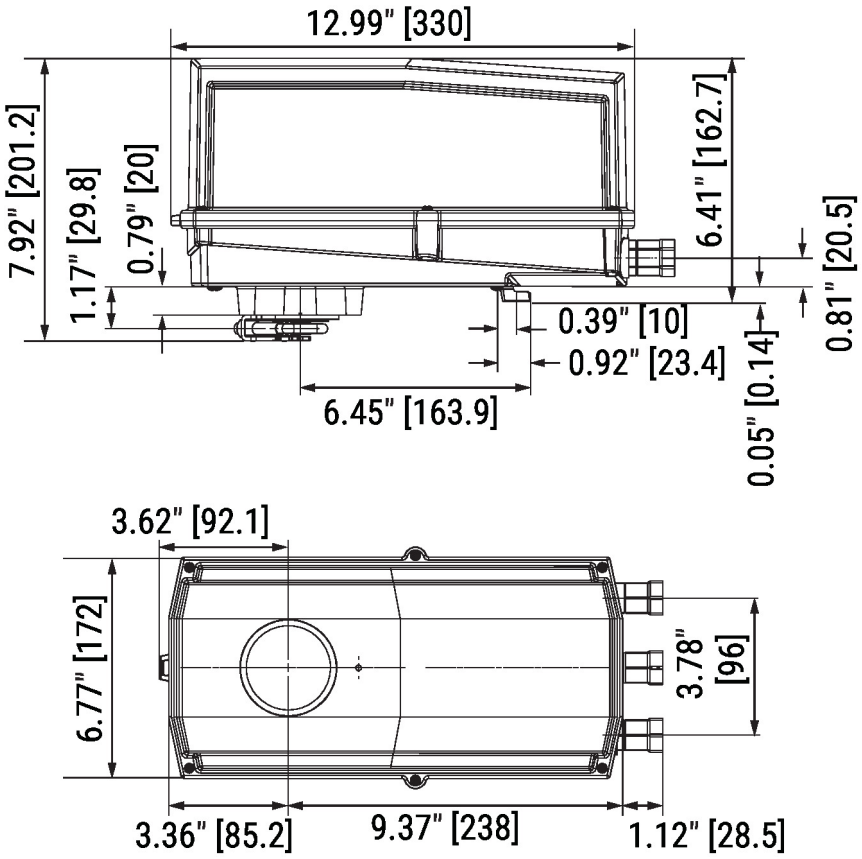
Primary - Secondary



NEMA 4 Heater Option



Dimensions


12.99" [330]
7.92" [201.2]
1.17" [29.8]
0.79" [20]
6.41" [162.7]
0.81" [20.5]
0.39" [10]
0.92" [23.4]
0.05" [0.14]
6.45" [163.9]
3.62" [92.1]
6.77" [172]
3.78" [96]
3.36" [85.2]
9.37" [238]
1.12" [28.5]