

BACnet Interface Description



PR Actuator Rotary actuator for butterfly valves

Edition 2024-01 / V3.08



Contents

Protocol Implementation Conformance Statement – PICS

| | |
|---|---|
| General information | |
| BACnet Interoperability Building Blocks supported (BIBBs) | 4 |
| BACnet MS/TP | |
| Parametrisation | |
| Standard object types supported | 5 |

BACnet object description

6-7

Protocol Implementation Conformance Statement – PICS

General information

| | |
|--------------------------------|--|
| Date | 01.12.2023 |
| Vendor Name | BELIMO Automation AG |
| Vendor ID | 423 |
| Product Name | Butterfly Valve Actuator |
| Product Model Number | PR..A-BAC-.. |
| Application Software Version | Modbus Module V1.0 |
| Firmware Revision | BTL:0002 B:0001 |
| BACnet Protocol Revision | 12 |
| Product Description | Rotary actuator with high torque |
| BACnet Standard Device Profile | BACnet Application Specific Controller (B-ASC) |
| Segment Capability | No |
| Data Link Layer Options | MS/TP Manager Node |
| Device Addressing Binding | No static device binding supported |
| Networking Options | None |
| Character Sets Supported | ISO 10646 (UTF-8) |
| Gateway Options | None |
| Network Security Options | Non-secure device |
| Conformance | Listed by BTL |

BACnet Interoperability Building Blocks supported (BIBBs)

Data sharing – ReadProperty-B (DS-RP-B)
 Data sharing – ReadPropertyMultiple-B (DS-RPM-B)
 Data sharing – WriteProperty-B (DS-WP-B)
 Data sharing – COV-B (DS-COV-B)
 Device management – DynamicDeviceBinding-B (DM-DDB-B)
 Device management – DynamicObjectBinding-B (DM-DOB-B)
 Device management – DeviceCommunicationControl-B (DM-DCC-B)

BACnet MS/TP

| | |
|----------------------|---|
| Baud Rates | 9'600, 19'200, 38'400, 76'800, 115'200 (Default: 38'400) |
| Address | 0...127 (Default: 1) |
| Number of Nodes | Max. 32 (without repeater), 1 full bus load |
| Terminating Resistor | 120 Ω |

Parametrisation

| | |
|------|----------------------|
| Tool | Belimo Assistant App |
|------|----------------------|



All writeable objects which are persistent are **not** supposed to be written on a regular basis.

Standard object types supported

| Object type | Optional properties | Writeable properties |
|-------------------------|---|---|
| Device | Description Location Active COV Subscriptions Max Manager Max Info Frames Profile Name | Object Identifier Object Name Location Description APDU Timeout (1'000...60'000) Number of APDU Retries (0...10) Max Manager (1...127) Max Info Frames (1...255) |
| Analog Input [AI] | Description COV Increment | COV Increment |
| Analog Value [AO] | Description COV Increment | Present Value COV Increment Relinquish Default |
| Analog Value [AV] | Description COV Increment | Present Value COV Increment |
| Binary Input [BI] | Description Active Text Inactive Text | – |
| Multi-state Input [MI] | Description State Text | – |
| Multi-state Output [MO] | Description State Text | Present Value Relinquish Default |
| Multi-state Value [MV] | Description State Text | Present Value |

The device does not support the services CreateObject and DeleteObject.
The specified maximum length of writeable strings is based on single-byte characters.

- Object name 32 char
- Location 64 char
- Description 64 char

Service processing

The device supports the DeviceCommunicationControl services.
No password is required.

A maximum of 6 active COV subscriptions with a lifetime of 1...28'800 s (8 hours) are supported.

BACnet object description

| Object name | Object type [Instance] | Description Comment, Status_Flags | Values | COV increment | Access |
|-------------------------|---------------------------|--|--------------------------------|-----------------------------|--------|
| Device | Device [Inst.No] | BACnet internetwork-wide unique number for device identification. This value plus the parameterized MAC address (0...127) defines the Device-ID | 0...4'194'302 Default: 1 | - | W |
| RelPos | AI[1] | Relative position in % Overridden = true, if gear train is disengaged | 0...100 | 0.01...100 Default: 1 | R |
| AbsPos | AI[2] | Absolute position in degrees The unit depends on the device: [°] for actuators with rotary movement [mm] for actuators with linear movement Overridden = true, if gear train is disengaged | 0...max. angle / stroke | 0.01...65'535 Default: 1 | R |
| SpAnalog | AI[6] | Analog setpoint in % Shows setpoint in % if actuator is controlled by analog signal (SpSource MV[122] is analog(1)). If SpSource MV[122] is Bus(2) then Out_Of_Service is TRUE. | 0...100 | 0.01...100 Default: 1 | R |
| Sens1Analog | AI[20] | Sensor 1 as analog value in V / Ω / – / °C / °F Current value of sensor 1 in case Sens1Type MV[220] is Active. If Sens1Type MV[220] is not Active(2) or SpSource MV[122] is Analog(1) then Out_Of_Service is TRUE. | – | 0.01...1'000 Default: 1 | R |
| Sens2Analog | AI[21] | Sensor 2 as analog value in V / Ω / – / °C / °F Current value of sensor 2 in case Sens2Type MV[221] is Active(2). If Sens2Type MV[221] is not Active(2) or SpSource MV[122] is Analog(1) then Out_Of_Service is TRUE. | – | 0.01...1'000 Default: 1 | R |
| SpRel | AO[1] | Relative setpoint in % Setpoint for actuator between 0 and Max AV[98] if controlled via bus. If SpSource MV[122] is Analog(1) then Out_Of_Service is TRUE. | 0...100 Default: 0 | 0.01...100 Default: 1 | C |
| Max | AV[98] | Max setpoint in % Max has to be ≥ Min +30% | Min +30%...100 Default: 100 | 0.01...100 Default: 1 | W |
| Bus Watchdog | AV[130] | Timeout for Bus Watchdog in s 0 = watchdog deactivated If the Present_Value is not ZERO, the implementation tracks write procedures to Present_Value of AO[1] and MO[1]. If the Present_Value of AO[1] or MO[1] is written, the timer is reset. Upon timeout the Priority_Array of the AO[1] is cleared and the Relinquish_Default becomes valid. In hybrid mode (SpSource MV[122] is Analog(1)), the implementation tracks write procedures to Present_Value of MO[1]. | 0...3'600 Default: 0 | 0.01...1'000 Default: 1 | W |
| Fail-Safe Bridging Time | AV[131] | Fail-safe bridging time in s In the event of a power failure, the actuator will remain stationary in accordance with the set bridging time. Only for electronic fail-safe actuators. | 0...10 Default: 0 | 1...10 Default: 1 | W |
| Fail-Safe Position | AV[132] | Fail-safe position in % In the event of a power failure, the actuator will move into the selected fail-safe position, taking into account the bridging time that has been set. The rotary knob must be set to "Tool" position. Only for electronic fail-safe actuators. | 0...100 Default: 0 | 0.01...100 Default: 1 | W |

| Object name | Object type [Instance] | Description Comment, Status_Flags | Values | Access |
|------------------|---------------------------|---|--|--------|
| Sens1Switch | BI[20] | Sensor 1 as switch Indicates value on sensor 1 in case Sens1Type MV[220] is Switch(5). If Sens1Type MV[220] is not Switch(5) or SpSource MV[122] is Analog(1) then Out_Of_Service is TRUE. | Inactive_Text: Inactive Active_Text: Active | R |
| Sens2Switch | BI[21] | Sensor 2 as switch Indicates value on sensor 2 in case Sens2Type MV[221] is Switch(5). If Sens2Type MV[221] is not Switch(5) or SpSource MV[122] is Analog(1) then Out_Of_Service is TRUE. | Inactive_Text: Inactive Active_Text: Active | R |
| BusTermination | BI[99] | Bus termination Indicates if bus termination (120 Ω) is enabled. Bus termination can be set with the configuration tools. | Inactive_Text: Inactive Active_Text: Active | R |
| SummaryStatus | BI[101] | Summary status Summary of all Status (MI[106], MI[110]) | Inactive_Text: OK Active_Text: Not OK | R |
| InternalActivity | MI[100] | Internal activity Test: Internal test running, activated by bus | 1: None 2: Test 3: – | R |
| StatusActuator | MI[106] | Status actuator Actuator cannot move: Mechanical overload, e.g. blocked actuator, etc. Gear train disengaged: Button is pressed. Mechanical travel increased: The actuator has been moved outside the adapted working range. | 1: OK 2: Actuator cannot move * 3: Gear train disengaged 4: Mechanical travel increased * | R |
| StatusDevice | MI[110] | Status device Indicates general status about the device. Bus Watchdog triggered: Timeout for Bus Watchdog expired. | 1: OK 2: Bus Watchdog triggered | R |
| Override | MO[1] | Override control Overrides the setpoint (SpRel AO[1] or analog signal) with defined values. Use of Fast open / Fast close: Fast open and Fast close cycles lead to increased mechanical load. Usage should be limited to certain time-critical events (e.g. frost protection). | 1: None 2: Open 3: Close 4: Min_V _{min} 5: Mid_V _{mid} 6: Max_V _{max} 7: Fast open 8: Fast close Default: None(1) | C |
| Command | MV[120] | Initiate function Initiation of actuator functions for service and test. After command is sent, value returns to None(1). With Reset(4), all status in StatusActuator MI[106] can be reset. | 1: None 2: – 3: Test 4: Reset Default: None(1) | W |
| SpSource | MV[122] | Setpoint source If Analog(1) then actuator is controlled by analog signal 0...10 V on wire 3. If Bus(2) then setpoint via bus SpRel AO[1]. | 1: Analog 2: Bus Default: Bus(2) | W |
| Sens1Type | MV[220] | Sensor 1 type If SpSource MV[122] is Analog(1) then Out_Of_Service is TRUE. | 1: None 2: Active 3: Passive_1K 4: Passive_20K 5: Switch 6: PT1000_C 7: NI1000_C 8: NTC10K2_C 9: PT1000_F 10: NI1000_F 11: NTC10K2_F Default: None(1) | W |
| Sens2Type | MV[221] | Sensor 2 type If SpSource MV[122] is Analog(1) then Out_Of_Service is TRUE. | 1: None 2: Active 3: Passive_1K 4: Passive_20K 5: Switch 6: PT1000_C 7: NI1000_C 8: NTC10K2_C 9: PT1000_F 10: NI1000_F 11: NTC10K2_F Default: None(1) | W |

Description Access: R = Read, W = Write, C = Commandable with priority array
* Status information must be reset Command MV[120] -> Reset(4)

All inclusive.

Belimo as a global market leader develops innovative solutions for the controlling of heating, ventilation and air-conditioning systems. Damper actuators, control valves, sensors and meters represent our core business.

Always focusing on customer value, we deliver more than only products. We offer you the complete product range for the regulation and control of HVAC systems from a single source. At the same time, we rely on tested Swiss quality with a five-year warranty. Our worldwide representatives in over 80 countries guarantee short delivery times and comprehensive support through the entire product life. Belimo does indeed include everything.

The "small" Belimo devices have a big impact on comfort, energy efficiency, safety, installation and maintenance.

In short: Small devices, big impact.



5-year warranty



On site around the globe



Complete product range



Tested quality



Short delivery times



Comprehensive support



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